

## Cala Touch KNX Room controllers with touch display

Item numbers Cala KNX T: 70800 (pure white RAL 9010) 70802 (jet black RAL 9005)

Cala KNX TH: 70810 (pure white RAL 9010) 70812 (jet black RAL 9005) Cala KNX AQS/TH: 70820 (pure white RAL 9010) 70822 (jet black RAL 9005)



Illustration with frame (not included in the deliverables)



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	Elsner Elektronik GmbH • Sohlengrund 16 • 75395 Ostelsheim • Germany Room controller Cala Touch KNX • from ETS programme version 3.0, software version 0.3.3 Version: 28.04.2020 • Technical changes and errors excepted.	

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Installation, inspection, commissioning and troubleshooting of the device must only be carried out by a competent electrician.

This manual is amended periodically and will be brought into line with new software releases. The change status (software version and date) can be found in the contents footer. If you have a device with a later software version, please check

www.elsner-elektronik.de in the menu area "Service" to find out whether a more up-todate version of the manual is available.

### Clarification of signs used in this manual

$\wedge$	Safety advice.
	Safety advice for working on electrical connections, components, etc.
DANGER!	indicates an immediately hazardous situation which will lead to death or severe injuries if it is not avoided.
WARNING!	indicates a potentially hazardous situation which may lead to death or severe injuries if it is not avoided.
CAUTION!	indicates a potentially hazardous situation which may lead to trivial or minor injuries if it is not avoided.
ATTENTION!	indicates a situation which may lead to damage to property if it is not avoided.
ETS	In the ETS tables, the parameter default settings are marked by underlining.

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This document describes the functions for ALL device models. Please check the information at the beginning of the chapter and in the text which describes the functions available for the respective individual models.

### 1. Description

The **Room Controller Cala Touch KNX** for the KNX bus system measures various ambient climate. Via the bus, the indoor sensor can receive external values and process them further with its own data to a total value (mixed value, e.g. room average).

All measured values can be used for the control of threshold value-dependent switching outputs. States can be linked via AND logic gates and OR logic gates. Multi-functional modules change input data as required by means of calculations, querying a condition, or converting the data point type. In addition, an integrated manipulated variable comparator can compare and output variables that were received via communication objects.

Integrated PI-controllers control ventilation (according to humidity or  $CO_2$ -concentration) and/or heating/cooling (according to temperature), depending on the respective model.

**Cala Touch KNX** features a touch display that shows various display and control pages depending on the individual configuration. There is one page available that shows the current measured values, a menu area to adjust device settings and pages with touch control elements for internal temperature control, for light (manual switching or dimming), for shades or windows (manual operation).

**Cala Touch KNX** is supplemented with a frame of the switch series used in buildings, and thus fits seamlessly into the interior fittings.

#### Common features in all models:

- Colour touch display with display and operating pages for
  - 1× display of current measured values
  - 1× display of bus data (4 universal spaces)
  - 1× temperature control (incl. mode change, indication whether heating/ cooling active); can also be used as an extension unit for operating another controller
  - 3x drive operation (shading, window) with buttons, slider, position display (incl. slat position)
  - 3× switching or dimming of light (with percentage display)
  - 1× RGB light control
  - 1× light colour temperature setting
  - 1× HCL control (adaption of light color temperature over adjustable periods of time)
  - 1× scenes (4 scenes with recall, storage, status indication)
  - weekly timer switch with 8 periods

- 2× info page (each displays 2 text objects)
- device settings
- Screen saver (clock, clock/indoor/outdoor temperature alternately, off) may be switched on or off
- Key tone may be switched on or off
- 4 inputs for binary contacts or T-NTC temperature sensor.
- 8 AND and 8 OR logic gates each with 4 inputs. All switching events as well as 16 logic inputs (in the form of communications objects) can be used as inputs for the logic gates. The output from each gate can be configured optionally as 1-bit or 2 x 8-bit
- 8 multi-function modules (computers) for changing the input data by calculations, by querying a condition or by converting the data point type
- **4 manipulated variable comparators** to output minimum, maximum or average values. 5 inputs each for values received via communication objects
- **Summer compensation** for cooling systems. A characteristic curve matches the target temperature in the room to the external temperature and sets the minimum and maximum target temperature values

### Cala Touch KNX AQS/TH functions (no. 70820, 70822):

- Measuring the CO<sub>2</sub>-concentration of the air, the temperature and air humidity (relative, absolute), each with mixed value calculation. The share of internal measurement value and external value can be set as a percentage
- Bus message, whether the values for temperature and air humidity are within the comfort field (DIN 1946). Dew point calculation
- Threshold values can be adjusted per parameter or via communication
   objects
- PI-controller for heating (one or two-level) and cooling (one or two-level) according to temperature. Regulation according to separate set points or basic set point temperature. Fan coil control
- **PI controller for ventilation** according to humidity and CO<sub>2</sub>-concentration: Ventilate/Air (one-level) or Ventilate (one or two-levels)

### Cala Touch KNX TH functions (no. 70810, 70812):

- **Temperature** and **air humidity** measurement (relative, absolute), in each case with **mixed value calculation**. The share of internal measurement value and external value can be set as a percentage
- Bus message, whether the values for temperature and air humidity are within the **comfort field** (DIN 1946). **Dew point** calculation
- Threshold values can be adjusted per parameter or via communication
   objects
- PI-controller for heating (one or two-level) and cooling (one or two-level) according to temperature. Regulation according to separate setpoints or basic set point temperature. Fan coil control
- **PI controller for ventilation** according to humidity: Ventilate/Air (one-level) or Ventilate (one or two-level)

#### Cala Touch KNX T functions (no. 70800, 70802):

- Measuring the Temperature with a mixed value calculation. The share of internal measurement value and external value can be set as a percentage
- Threshold values can be adjusted per parameter or via communication
   objects
- PI-controller for heating (one or two-level) and cooling (one or two-level) according to temperature. Regulation according to separate set points or basic set point temperature. Fan coil control

Configuration is made using the KNX software ETS. The **product file** can be downloaded from the Elsner Elektronik website on **www.elsner-elektronik.de** in the "Service" menu.

### 1.0.1. Deliverables

- Housing with display
- Base plate
- Analogue/digital supply line
- Additionally required (not included in the deliverables):
- Junction box Ø 60 mm, 42 mm deep
- Frame (for insert 55 x 55 mm), compatible to the switch scheme used in the building

1.1.	Technical	specifications

Material	Real glass, plastic	
Display	Visible diagonal: 2.3 inches (59 mm) Resolution: 320 × 240 pixels	
Colours	<ul> <li>black glass, black housing (jet black RAL 9005)</li> <li>white glass, white housing (pure white RAL 9010)</li> </ul>	
Assembly	Flush mounting (Wall mounting in junction box Ø 60 mm, 42 mm deep)	
Protection category	IP 20	
Dimensions	approx. 55 $\times$ 55 $\times$ 35 (W $\times$ H $\times$ D, mm), mounting depth approx. 7 mm	
Total weight	approx. 90 g (incl. supply line, base plate	
Ambient temperature	Operation -20+70°C, storage -30+70°C	
Ambient humidity	max. 95% RH, avoid condensation	
Operating voltage	KNX bus voltage	
Bus current	max. 18 mA	
Data output	KNX +/- bus connector terminal	
BCU type	Integrated microcontroller	
PEI type	0	
Group addresses	max. 2000	
Assignments	max. 2000	

Communication objects	Cala Touch KNX AQS/TH: 471 Cala Touch KNX TH: 433 Cala Touch KNX T: 379		
Inputs	4× analogue/ digital, max. cable length 10 m.		
measuring range T-NTC tem- perature sensor on Cala input	-40°C+80°C		
CO <sub>2</sub> -sensor (for Cala Touch KNX AQS/TH):			
CO <sub>2</sub> -measuring range	3005000 ppm		
CO <sub>2</sub> resolution	1 ppm		
Temperature sensor (for Cala Touch KNX AQS/TH, Cala Touch KNX TH, Cala Touch KNX T):			
Temperature measuring range	-20+70°C		
Temperature resolution	0.1°C		
Humidity sensor (for Cala Touch KNX AQS/TH, Cala Touch KNX TH):			
Humidity measuring range 0% HR 100% HR			
Humidity resolution	0.1%		
Humidity drift	± 0.5% RH per year in normal atmosphere		

The product is compliant with the provisions of EC guidelines.

### 1.1.1. Measuring accuracy

Measurement deviations due to sources of interference (see chapter *Installation location*) must be corrected in the ETS in order to ensure the specified accuracy of the sensor (offset).

For a correct **CO<sub>2</sub> measurement** it is necessary to install the device in a windproof socket. After applying the operating voltage, it can take up to 15 minutes until the **CO<sub>2</sub> measured value** is output correctly.

During **temperature measurement**, the self-heating of the device is taken into consideration by the electronics. It is compensated for by the software, therefore the displayed/output inside temperature measuring value is correct.

### 2. Installation and commissioning

### 2.1. Installation notes

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Installation, testing, operational start-up and troubleshooting should only be performed by an electrician.



#### CAUTION! Live voltage!

There are unprotected live components inside the device.

- National legal regulations are to be followed.
- Ensure that all lines to be assembled are free of voltage and take precautions against accidental switching on.
- Do not use the device if it is damaged.
- Take the device or system out of service and secure it against unintentional use, if it can be assumed, that risk-free operation is no longer guaranteed.

The device is only to be used for its intended purpose. Any improper modification or failure to follow the operating instructions voids any and all warranty and guarantee claims.

After unpacking the device, check it immediately for possible mechanical damage. If it has been damaged in transport, inform the supplier immediately.

The device may only be used as a fixed-site installation; that means only when assembled and after conclusion of all installation and operational start-up tasks and only in the surroundings designated for it.

Elsner Elektronik is not liable for any changes in norms and standards which may occur after publication of these operating instructions.

### 2.2. Installation location

The sensor is installed in a flush-mounted box (Ø 60 mm, 42 mm deep).



### The sensor may only be installed and used in dry interior spaces. Avoid condensation.

When selecting an installation location, please ensure that the measurement results are affected as little as possible by external influences. Possible sources of interference include:

- Direct sunlight
- Draughts from windows and doors
- Draughts from ducts which lead to the junction box in which the sensor is mounted from other rooms.
- Warming or cooling of the building structure on which the sensor is mounted, e.g. due to sunlight, heating or cold water pipes
- Connection lines, which lead from warmer or colder areas to the sensor

Temperature variations from such sources of interference must be corrected in the ETS in order to ensure the specified accuracy of the sensor (temperature offset).

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### 2.3. Device design

View with frame and base plate.

Fig. 1a





Fig. 2

Analogue/digital supply line inputs: Input 1: white / black (GND) Input 2: yellow / black (GND) Input 3: purple / black (GND) Input 4: blue / black (GND)

Fig. 1b

### 2.4. Sensor assembly

First, place the wind-proof box with the supply connection. Seal the inlet tubes as well, in order to prevent drafts.

Then screw the base plate onto the socket and position the frame of the switch range on top of this. Connect the bus lines +/- to the black-red KNX plug and plug the KNX

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plug into the intended slot (no. 8). If required, connect the analogue/digital inputs via the breakout cable that is included in the delivery.

Insert the housing firmly onto the metal frame using the catches so that sensor and frame are fixed together.

### 2.5. Notes on mounting and commissioning

Never expose the device to water (e.g. rain) or dust. This can damage the electronics. You must not exceed a relative humidity of 95%. Avoid condensation.

After the bus voltage has been applied, the device will enter an initialisation phase lasting a few seconds. During this phase no information can be received or sent via the bus.

### 3. Addressing the equipment

The equipment is delivered with the bus address 15.15.255. You can program a different address in the ETS by overwriting the address 15.15.255 or by teaching the device via the programming button.

The programming button can be reached through the opening on the rear of the housing; it is recessed. Use a thin object to reach the button, e.g. a  $1.5 \text{ mm}^2$  wire.

### 4. Maintenance and care

Fingerprints on the display and the housing are best removed with a cloth moistened with water or a microfibre cloth. Do not use an abrasive cleaning agent or aggressive cleansing agents.

# 5. Operating the device via the touch display

The available display and operating options on the device depend on the ETS "menu" settings. Here you decide which menus are shown.

You call up the different menus on the display by swiping to the right or left. You navigate to sub-menus via the touch keys and the navigation bar at the bottom of the screen using the symbols Back (= cancel), start page, OK (= confirm).

Other display settings can be adjusted in the ETS in the "Display" and "Button tone" sections. However, you may also use the "Settings" menu on the display itself if it is released for display.

### 5.1. Menu overview

••••• Navigation by swiping, top menu level.

Cancel key. Go up one menu level without saving.

**Start page** key. To start page without saving.

**OK** Confirm key. Save and go up one menu level.



Room Controller Cala Touch KNX • Version: 28.04.2020 • Technical changes and errors excepted.

### 5.2. Device settings

The adaptation of display settings on the device is only possible if the "Settings" have been activated in the ETS setting item "Menus".

Menus, page 60

You can modify screen settings on the

- "Settings" display pages
- switch the button tone on or off
- show the device and application version

Fig. 4: "Settings" menu



(1) The dots on the lower display edge symbolise the individual menu pages in the main menus. The currently selected position is marked in colour. Swipe to the left or right on the display to show the other menu pages.

### 5.2.1. Display settings

Tap on the screen symbol to call up the screen settings.

Here you can adjust

- the display brightness
- select the type of screen saver
- determine the start page
- decide if you want the display to switch to the start page if it has not been touched for a certain period of time.

Fig. 5: Menu Settings > Display



(1) The touch keys on the navigation bar in the overview and in all sub-menus allow you to

 $\leftarrow$  cancel and return to the previous menu level without saving

jump to the start page without saving

and also to confirm and return to the previous menu level after saving from the settings screens

### **Display brightness**

 $\sim$ 

Tap on the brightness symbol to call up the display brightness settings.

Fig. 6: Menu Settings > Display > Brightness



(1) Tap on the left part of the screen (-) to reduce screen brightness. Tap on the right part (+) to increase brightness. Settings range 1...100%. If you touch - or + for a longer time, the brightness changes in 5% steps.

(2) The navigation bar keys take you back to the start page or let you confirm the changes with **OK**.

#### Screen saver



Tap the screen saver symbol to select the type of screen saver or switch the screen saver off.

Fig. 7: Menu Settings > Display > Screen saver



(1) Select the desired screen saver function. The selected function is shown in blue.

Screen saver "clock" becomes active after the period set in the ETS. According to the ETS setting, the date/time or date/time with indoor and outdoor temperature are displayed alternately.



Screen is switched off after the period set in the ETS.



Screen saver not active

(2) The navigation bar keys take you back to the start page or let you confirm the changes with **OK**.

### Start display

Tap the start page symbol to modify the start page.

The start page is the menu that is shown after startup and pressing the house symbol. One may also set the display screen to jump back to the start screen by itself if the screen has not been touched for a certain period of time (see next setting). Fig. 8: Menu Settings > Display > Screen saver



(1) Switch to the desired start page menu with the left/right arrow keys. The name of the menu and if applicable the symbol are displayed.



Only those menus are shown that have been activated for display in the ETS (see chapter *Menus*, page 60).

(2) The navigation bar keys take you back to the start page or allow you to confirm the changes with **OK**.

#### Switch to start page



Tap on the symbol "Switch to start page" in order to switch automatic return to the start page on or off.





(1)Activate or deactivate the function by tapping on the words **No** or **Yes** or drag the slide bar to the desired setting. The wait time for the switch is pre-set in the ETS (see chapter *Display*, page 58).

(2) The navigation bar keys take you back to the start page or allow you to confirm the changes with **OK**.

### 5.2.2. Button tone

Tap on the loudspeaker symbol to call up the button tone settings.

The button tone may be emitted as an acoustic acknowledgement when a touch key is activated.





(1)Activate or deactivate the function by tapping on the words **Off** or **On** or drag the slide bar to the desired setting.

(2) The navigation bar touch keys allow you to

 $\leftarrow$  cancel and return to the previous menu level without saving



jump to the start page without saving

 $\operatorname{confirm}$  and return to the previous menu level after saving from the settings  $\operatorname{screens}$ 

### 5.2.3. Version



Tap on the software symbol to show the device version.

Fig. 11: Menu Settings > Version



(1) This shows the software version and the application version (VD or KNXprod file) that is needed for the device.

(2) The navigation bar touch keys allow you to





jump to the start page without saving

 $\operatorname{confirm}$  and return to the previous menu level after saving from the settings  $\operatorname{screens}$ 

### 5.3. Sensor system (measured value display)

The display of measured values on the device is only possible if the "Sensor system" has been activated in the ETS setting item "Menus".

Menus, page 60.



Fig. 12: Menu Sensor system, example Cala KNX AWS/TH

Fig. 13 a+b: Sensor system menu: Cala KNX TH, Cala KNX T



On the display page "Sensor system, the current measuring values from the sensor (2) are displayed underneath the (1) symbols for the measuring variables. Depending on the model, this can be temperature, air humidity and/or the carbon dioxide level of the air.

- The temperature is displayed in degree Celsius.
- The relative air humidity is displayed in %.
- **CO**<sub>2</sub> The CO<sub>2</sub> content in the air is shown in ppm (parts per million), with 1000 ppm = 0,1%.

 $\rm CO_2$  levels between 300 ppm and 1000 ppm are referred to as fresh air. From 1000 ppm to 2000 ppm the air is considered stale.

In all cases, this is the measuring value from the device.

(3) The dots on the lower display edge symbolise the individual menu pages in the main menus. The currently selected position is marked in colour. Swipe to the left or right on the display to show the other menu pages.

### 5.4. Temperature control

The room temperature can be set individually on the "Temperature controller" operating page.

The manual temperature setting on the device is only possible if "Temperature control" has been activated in the ETS setting item "Menus".

Menus, page 60 and *Temperature control*, page 61.

Fig. 14: Temperature control menu:



### (1) name

- (2) current nominal value
- (3) current mode (option)
- (4) fan level information / fan coil (option)

### (3) Changing the mode:

- Tapping on the mode symbol displays the temperature control modes that have been approved for display selection in the ETS. The active mode is shown in colour (red for heating, blue for cooling).
- In order to select a different mode, first switch to the symbol of the desired mode by tapping.
- Then remain on the symbol a little longer. If the button tone is active, you will receive an acoustic feedback. The mode is now active, and the colour for this symbol changed from white to coloured.

The modes change in the following sequence:

Comfort (day, present), heating or cooling active



Standby (day, brief absence), heating or cooling active



Eco (night), heating or cooling active

Building protection (prolonged absence, e.g. vacation), heating or cooling active

The small additional symbol shows whether heating or cooling is active (control value unequal to zero, use depends on the connected system).



As long as Eco mode is active, there is an additional symbol for "comfort extension". This option may also be blocked in the ETS (symbol does not appear for selection).

Remain on the comfort extension symbol for a little longer in order to briefly switch back to comfort operation. This allows the user to maintain the nominal comfort value for a longer time, e.g. when having guests. The duration of this comfort extension period is set in the ETS. The remaining time is shown next to the symbol. After the comfort extension period is terminated, the system returns to Eco mode.

(4) The current mode and level in red are displayed in the fan coil icon. "A" means "automatic", "M" manual ".

By tapping on the fan icon, the level can be changed manually. By repeatedly touching, the display changes to M0 (manual Off), M1 (manual level 1), M2 (manual level 2), M3 (manual level 3) and back to AX (automatic).

To confirm the selection and activate the displayed mode, stay on the icon for a little longer. When the button tone is activated, an acoustic feedback occurs. The mode is now active, the color of the symbol has changed from white to coloured.

(5) The nominal value for the current mode can be adjusted by tapping on the minus and/or plus symbol.



If the manual modification of the nominal value is blocked in one mode, the symbol "Manual blocked" is briefly shown when an attempt is made to modify the value.

(6) The dots on the lower display edge symbolise the individual menu pages in the main menus. The currently selected position is marked in colour. Swipe to the left or right on the display to show the other menu pages.

### 5.5. Light

Lights can be switched or dimmed on the maximum of three operating pages "Light".

The manual temperature setting on the device is only possible if "Light" has been activated in the ETS setting item "Menus". The maximum number of light pages is three. *Menus*, page 60 and *Light 1-3*, page 62

Depending on the type of lamp and the settings made in the ETS, the display page "Light" shows various elements.



#### Switching over an On/Off area

If Switching via an area On/Off has been selected, the display shows:

(1) name

(2) area with the selected symbol

The symbol is grey when switched off, and blue when on.

The area switches between on and off. If dimming is set in addition, touch the area for longer to dim. This process is shown by repeated dimming of the symbol. When dimming, any new contact also switches, i.e. the dimming increases in brightness or decreases alternately.

(3) The dots on the lower display edge symbolise the individual menu pages in the main menus. The currently selected position is marked in colour. Swipe to the left or right in this area to show the other menu pages.



#### Switching via two areas On - Off

Fig. 16: Light menu, two areas (switching)

#### If Switching via two areas On - Off has been selected, the display shows: (1) name

(2) two areas with the selected symbol

The symbol is grey when switched off, and blue when on.

Tap on the left part of the screen to switch off the light. Tap on the right part to switch on.



(2) If additional dimming is possible, a minus and a plus symbol are shown. Touching the left part of the screen (-) dims down. Touching the right part (+) dims up.

(3) Alternatively, swipe left (darker) or right (brighter) on the slider bar that is shown in the *lower* part of the display. The slide bar position shows the current brightness of the lamp in percent.

(4) The current brightness value in percent is displayed if this has been activated in the ETS.

(5) The dots on the lower display edge symbolise the individual menu pages in the main menus. The currently selected position is marked in colour. Swipe to the left or right in the *top* half of the display to show the other menu pages.

### 5.6. Drive (shading, window)

Blinds, shutters, awnings can be moved up and down, or windows can be opened and closed on the maximum of three "Drive" operating pages.

Manual operation setting of shading or windows on the device is only possible if "Drive" has been activated in the ETS setting item "Menus". The maximum number of drive pages is three.

Menus, page 60 and Drive 1-3, page 63



(2) keys for up and down.

(3) slide bar (option)

(4) current drive position (option)

The key reaction (standard, inverted, comfort, dead man) can be set in the ETS.

Drive 1-3, page 63

(3) The (a) travel position and in the case of blinds also the (b) slat position can be displayed as percentage values.

As soon as a travel position or a slide bar is available, icons for awning, roller shutter, blind and blind slats are displayed.

(4) The slide bar allows you to quickly adjust the (a) movement position. In the case of blinds, a slider control for the (b) slat position can also be displayed. The slide bar position shows the current movement position in percent. Depending on the ETS settings, it can start with 0% from top or bottom.

(5) The dots on the lower display edge symbolise the individual menu pages in the main menus. The currently selected position is marked in colour. Swipe to the left or right on the display to show the other menu pages.

### 5.7. Scenes

Up to four individual scenarios can be called up or saved on the "Scenes" operating page.

Scene control on the device is only possible if the individual "Scenes" have been activated in the ETS setting item "Menus".

Menus, page 60 and Scenes, page 64

#### Fig. 19: Menu Scenes



The "Scenes" display page is divided into four areas for calling and storing four scenes. The menu page shows the

(1) name entered in the ETS.

(2) Each scene area is also named individually.

The basic setup of the scenes, such as the assignment of the functions, takes place in the ETS

💷 Scenes, page 64

A scene is called up by briefly tapping in the scene area. If storage has been activated in the ETS, the current settings of the assigned functions can be transferred to the scene memory by touching the area for a longer time. When called, the new settings will be executed from now on.

The current status of a scene can be displayed (if activated in the ETS):

Name (text)	Scene
white	not active
white, flashes	executing
blue	executed (running, is active)

(3) The dots on the lower display edge symbolise the individual menu pages in the main menus. The currently selected position is marked in colour. Swipe to the left or right on the display to show the other menu pages.

### 5.8. Universal display

On the "Unversal display" display page, values can be displayed in up to four areas.

The page is only displayed if the "Universal display" has been activated in the ETS setting item "Menus".

Menus, page 60 and Universal display, page 65





The "Unversal display" menu page is divided into four areas, each of which can be used to display values.

- (1) name
- (2) display area with individual labeling
- (3) value
- (4) unit

The universal menu serves as a pure display / information page, not for the operation of functions.

The basic setup of the universal menu is done in the ETS.

💷 Universal display, page 65

(5) The dots on the lower display edge symbolise the individual menu pages in the main menus. The currently selected position is marked in colour. Swipe to the left or right on the display to show the other menu pages.

### 5.9. RGB control

On the "RGB control" operating page, the color of an RGB light can be individually adjusted.

Manual setting of a RGB color value on the device is only possible if the "RGB control" has been activated in the ETS setting item "Menus".

Menus, page 60 and RGB control, page 65



- (2) three color bars for red (R), green (G), and blue (B)
- (3) color result box
- (4) button for switching the light
- Function details can be set in the ETS.
- 📖 RGB control, page 65

(2) Change the color by using the color bars for RGB like three sliders. Swiping up or down in each bar increases or decreases the amount of color.

(3) The result is displayed in the color box on the top right. To send the newly set color to the bus, tap the color box. Only then the change will get visible when the light is on. Please note that the color and intensity of the controlled luminaire can have a different appearance than on the display of **Cala Touch KNX**.

(4) The key 1/0 at bottom right is a light switch. Tap the area to switch. When the light is off, the button is gray and shows a 0, when the light is on, it is blue and shows a 1.

(5) The dots on the lower display edge symbolise the individual menu pages in the main menus. The currently selected position is marked in colour. Swipe to the left or right on the display to show the other menu pages.

### 5.10. Color temperature

On the "Color temperature" operating page, the light temperature and brightness of a luminaire can be individually adjusted.

Manual setting of a light color temperature on the device is only possible if the "Color temperature" has been activated in the ETS setting item "Menus".

Menus, page 60 and Color temperature, page 66



(2) slider to change the brightness (dimming)

(3) current brightness value in %

(4) current colour temperature value in Kelvin

(5) slider to change the color temperature value

(6) buttons -/+ for switching or dimming brightness

All changes are transferred directly to the bus and are immediately effective/visible.

Function details can be set in the ETS.

📖 Color temperature, page 66

(7) The dots on the lower display edge symbolise the individual menu pages in the main menus. The currently selected position is marked in colour. Swipe to the left or right on the display to show the other menu pages.

### 5.11. HCL control

A lighting scenario can be set on the "HCL control" operating page. The aim of the HCL control is to mimic the natural change in sunlight throughout the day by gradually adjusting the light temperature and brightness of the artificial lighting. This is to support the daily rhythm of humans, which is why this type of light control is called "Human Centric Lighting" (HCL).

The setting of the light adaption to the daily routine (Human Centric Lighting, HLC) on the device is only possible if the "HCL control" has been activated in the ETS setting item "Menus".

Menus, page 60 and HCL control, page 66



(2) button for activating or deactivating the entire HCL control

(3) button for switching between manual and automatic

(4) button for the sequence setting menus

(5) currently running sequence and the current values

As long as no time is received via the bus, "No time available" is displayed. As long as the current time is not covered by a sequence, "Time not in sequence" is displayed. Function details can be set in the ETS.

HCL control, page 66

In HCL control, the day can be divided into up to 8 sequences. For each sequence, that means each period, target values for color temperature and brightness in % are set. Between start value and end value (stop value), the controller calculates the course of the values linearly. It can be defined in the ETS as of which change the values are sent to the bus, thus how fine the gradations should be.

(2) The entire HCL control can be activated and deactivated with the On / Off button. The button displays the current status.

(3) The status Automatic (A) or Manual (M) is displayed and can also be changed by touching the button. Manual operation of the light via the bus or button will turn the HCL control inactive until reset or switch to "A" with this button.

The automatic reset can be set in the ETS and takes place either through an object or after the expiry of a time.

(4) Each sequence can be set and changed on the display of the **Cala Touch KNX**. Touch the settings button to enter the sequence area.



#### Fig. 24: Sequence selection

The numbers of all sequences released for use are displayed in white, locked sequences in gray. To release or lock a sequence, stay on the sequence button longer, until the color changes. When the keypad tone is activated, an acoustic feedback occurs.

A brief tap on the sequence button will take you to the configuration of the sequence.







#### Fig. 25: Sequence X setting

The start and stop times and the values of brightness and color temperature at the end of the sequence are displayed.

Touch the area with the times to change them.

Touch the area with the values to adjust them.

#### Fig. 26: Sequence X start/stop

Touch the individual areas for hour, minute, and second, the start and stop times to change them.

The selected field is then outlined in blue and the value can be changed with +/-.

With OK you confirm all values and leave the time setting.

### Fig. 27: Sequence X brightness/temperature

Touch the areas for brightness value and color temperature value to change them.

The selected field is then outlined in blue and the value can be changed with +/-.

With OK you confirm all values and leave the setting.

Cancel and return to the previous menu level without saving.

(6) The dots on the lower display edge symbolise the individual menu pages in the main menus. The currently selected position is marked in colour. Swipe to the left or right on the display to show the other menu pages.

### 5.12. Weekly timer

Use the 'Timer' operating page to modify up to 8 timer intervals. The KNX system functions that are to be switched by the weekly timer must be set in the ETS.

Setting the weekly timer on the device is only possible if the 'Settings' have been activated in the 'Menus' ETS setting item. Only the switching periods that are activated there are displayed. If necessary, the switching command can be blocked via the bus. *Menus*, page 60 and *Timer*, page 68

Fig. 28: Timer menu Timer switch 2 3 Time is in the time switch points 1 2 4

#### (1) Name

(2) To settings. Tap here to accept the changes.

(3) The information text shows if the current time is within one or multiple timer periods. If there is no time received via the bus, the 'No time available' message is displayed.

(4) The dots on the lower display edge symbolise the individual menu pages in the main menus. The currently selected position is marked in colour. Swipe to the left or right on the display to show the other menu pages.

Tap on the gear icon to accept the changes.

Timer switch selection			
1	2		
Ĵ			
Ti	mer switch	ı	
Start time	08:00:00	Day	
Stop time	16:00:00	Select	

# Sequence 1 Start/Stop Start 07 : 30 : 00Stopp 07 : 32 : 00 $\Leftrightarrow$ - + 0K

Transm. behav. on/offldown/up



#### Fig. 29: Timer selection

The numbers of all the switching timers activated are shown here. Tap on a number to enter the switching time modification view.

#### Fig. 30: Timer X setting

The start/stop time and the send behaviour are displayed.

Tap on the field with the times to change them.

Tap on the 'Select day' field to choose the days of the week.

Tap on the 'Send behaviour' field to change it.

#### Fig. 31: Sequence X start/stop

Tap the individual fields for hours, minutes and seconds, as well as the start and stop times to modify them.

The selected field is outlined in blue, and the value can be changed with the +/- buttons.

Confirm all the values with OK and leave the time adjustment mode.

#### Fig. 32: Sequence X weekday

Tap a field to activate the timer on this day. Active weekdays are marked in blue; inactive ones in grey.

Confirm your choice with OK and leave the settings


Fig. 33: Sequence X send behaviour

Change the send behaviour using the +/buttons. This way you can determine if the timer

- only switches on, and moves the shading down, and the window updated
- only switches off, and moves the drives in a safe position
- both switches on and off, and moves up and down.
- Confirm your choice with OK and leave the settings

Cancel and return to the previous menu level without saving.

## 5.13. Information pages

The two information pages display text information received via the bus.



(1) Name

 $\leftarrow$ 

(2) Texts from the bus system

(3) The dots on the lower display edge symbolise the individual menu pages in the main menus. The currently selected position is marked in colour. Swipe to the left or right on the display to show the other menu pages.

# 6. Transfer protocol

#### Units:

Temperatures in degrees Celsius Air humidity in % Absolute air humidity in g/kg and/or g/m<sup>3</sup>  $CO_2$  content in ppm Variables in %

# 6.1. List of all communications objects

#### Abbreviation flags:

- C Communication
- R Read
- W Write
- T Transfer
- U Update

No.	Text	Function	Flags	DPT type	Size		
Display and user interfaces (objects 1-124) for all models							
1	Software version	Output	R-CT	[217,001] DPT_Version	2 bytes		
21	Date / time	Input	-WCT	[19.001] DPT DateTime	8 bytes		
22	Date	Input	-WCT	[11.1] DPT_Date	3 bytes		
23	Time	Input	-WCT	[10.1] DPT TimeOfDay	3 bytes		
25	Screen brightness in %	Input	RWC-	[5.1] DPT_Scaling	1 byte		
26	Screen save (1=ON   0=OFF)	Input	RWC-	[1.1] DPT_Switch	1 bit		
27	Screen saver illumination (1=ON   0=OFF)	Input	RWC-	[1.1] DPT_Switch	1 bit		
28	Screen saver wait time in seconds	Input	RWC-	[7.005] DPT TimePeriodSec	2 bytes		
29	Screen no touch wait time in seconds	Input	RWC-	[7.005] DPT TimePeriodSec	2 bytes		
30	Display language	Input	RWC-	[234.001] DPT_LanguageC- odeAlpha2_ASCII	2 bytes		
31	Button tone (1=ON   0=OFF)	Input	RWC-	[1.1] DPT_Switch	1 bit		
34	Switch Light 1 on/off	Input/ Output	RWCT	[1.1] DPT_Switch	1 bit		
35	Dim Light 1	Output	R-CT	[3.7] DPT_Con- trol_Dimming	4 bit		

No.	Text	Function	Flags	DPT type	Size
36	Light 1 brightness	Input/ Output	RWCT	[5.1] DPT_Scaling	1 byte
37	Switch Light 2 on/off	Input/ Output	RWCT	[1.1] DPT_Switch	1 bit
38	Dim Light 2	Output	R-CT	[3.7] DPT_Con- trol_Dimming	4 bit
39	Light 2 brightness	Input/ Output	RWCT	[5.1] DPT_Scaling	1 byte
40	Switch Light 3 on/off	Input/ Output	RWCT	[1.1] DPT_Switch	1 bit
41	Dim Light 3	Output	R-CT	[3.7] DPT_Con- trol_Dimming	4 bit
42	Light 3 brightness	Input/ Output	RWCT	[5.1] DPT_Scaling	1 byte
44	Drive 1 long-term	Output	CT	[1.8] DPT_Up- Down	1 bit
45	Drive 1 short-term	Output	CT	[1.8] DPT_Up- Down	1 bit
46	Drive 1 movement position	Input/ Output	RWCT	[5.1] DPT_Scaling	1 byte
47	Drive 1 slat position	Input	-WCT	[5.1] DPT_Scaling	1 byte
48	Drive 1 operation lock	Input	-WC-	[1.1] DPT_Switch	1 bit
49	Drive 2 long-term	Output	CT	[1.8] DPT_Up- Down	1 bit
50	Drive 2 short-term	Output	CT	[1.8] DPT_Up- Down	1 bit
51	Drive 2 movement position	Input/ Output	RWCT	[5.1] DPT_Scaling	1 byte
52	Drive 2 slat position	Input	-WCT	[5.1] DPT_Scaling	1 byte
53	Drive 4 operation lock	Input	-WC-	[1.1] DPT_Switch	1 bit
54	Drive 3 long-term	Output	CT	[1.8] DPT_Up- Down	1 bit
55	Drive 3 short-term	Output	CT	[1.8] DPT_Up- Down	1 bit
56	Drive 3 movement position	Input / Output	RWCT	[5.1] DPT_Scaling	1 byte
57	Drive 3 slat position	Input	-WCT	[5.1] DPT_Scaling	1 byte
58	Drive 3 operation lock	Input	-WC-	[1.1] DPT_Switch	1 bit
60	Scene 1	Output	R-CT	[18.1] DPT_Scene- Control	1 byte
61	Scene 1 Status	Input	-WC-	[5.10] DPT Value_1_Ucount	1 byte
62	Scene 2	Output	R-CT	[18.1] DPT_Scene- Control	1 byte

No.	Text	Function	Flags	DPT type	Size
63	Scene 2 Status	Input	-WC-	[5.10] DPT Value_1_Ucount	1 byte
64	Scene 3	Output	R-CT	[18.1] DPT_Scene- Control	1 byte
65	Scene 3 Status	Input	-WC-	[5.10] DPT Value_1_Ucount	1 byte
66	Scene 4	Output	R-CT	[18.1] DPT_Scene- Control	1 byte
67	Scene 4 Status	Input	-WC-	[5.10] DPT Value_1_Ucount	1 byte
68	Universal menu Function1	Input	-WCT	Depending on setting	4 bytes
69	Universal menu Function 2	Input	-WCT	Depending on setting	4 bytes
70	Universal menu Function 3	Input	-WCT	Depending on setting	4 bytes
71	Universal menu Function 4	Input	-WCT	Depending on setting	4 bytes
72	Switch RGB control	Input / Output	RWCT	[1.1] DPT_Switch	1 bit
73	RGB control colour red, green and blue	Input / Output	RWCT	[232.600] DPT Colour_RGB	3 bytes
74	RGB control colour red	Input / Output	RWCT	[5.10] DPT Value_1_Ucount	1 byte
75	RGB control colour green	Input / Output	RWCT	[5.10] DPT Value_1_Ucount	1 byte
76	RGB control colour blue	Input / Output	RWCT	[5.10] DPT Value_1_Ucount	1 byte
77	Colour temperature	Input / Output	RWCT	[7.600] DPT_Ab- solute_Co- lour_Temperature	2 bytes
78	Colour temperature: switch bright- ness	Input / Output	RWCT	[1.1] DPT_Switch	1 bit
79	Colour temperature: dim brightness	Output	R-CT	[3.7] DPT_Con- trol_Dimming	4 bit
80	Colour temperature: brightness value in %	Input / Output	RWCT	[5.1] DPT_Scaling	1 byte
81	HCL control Brightness	Output	R-CT	[5.1] DPT_Scaling	1 byte
82	HCL control Color temperature	Output	R-CT	[7.600] DPT_Ab- solute_Co- lour_Temperature	2 bytes
83	HCL control start/stop	Input / Output	RWCT	[1.1] DPT_Switch	1 bit

No.	Text	Function	Flags	DPT type	Size
84	HCL control Automatic/Manual sta- tus	Ausgang	R-CT	[1.1] DPT_Switch	1 bit
85	HCL control Reset of automatic	Input	-WC-	[1.1] DPT_Switch	1 bit
86	HCL control Switch to manual with switching	Input	-WC-	[1.1] DPT_Switch	1 bit
87	HCL control Switch to manual with brightness	Input	-WC-	[5.1] DPT_Scaling	1 byte
88	HCL control Switch to manual with color temperature	Input	-WC-	[7.600] DPT_Ab- solute_Co- lour_Temperature	2 bytes
89	HCL control Sequence 1 release	Input / Output	RWCT	[1.1] DPT_Switch	1 bit
90	HCL control Sequence 2 release	Input / Output	RWCT	[1.1] DPT_Switch	1 bit
91	HCL control Sequence 3 release	Input / Output	RWCT	[1.1] DPT_Switch	1 bit
92	HCL control Sequence 4 release	Input / Output	RWCT	[1.1] DPT_Switch	1 bit
93	HCL control Sequence 5 release	Input / Output	RWCT	[1.1] DPT_Switch	1 bit
94	HCL control Sequence 6 release	Input / Output	RWCT	[1.1] DPT_Switch	1 bit
95	HCL control Sequence 7 release	Input / Output	RWCT	[1.1] DPT_Switch	1 bit
96	HCL control Sequence 8 release	Input / Output	RWCT	[1.1] DPT_Switch	1 bit
101	Timer switch 1 output	Output	R-CT	[1.1] DPT_Switch	1 bit
102	Timer switch 1 block	Input / Output	-WCT	[1.1] DPT_Switch	1 bit
103	Timer switch 2 output	Output	R-CT	[1.1] DPT_Switch	1 bit
104	Timer switch 2 block	Input / Output	-WCT	[1.1] DPT_Switch	1 bit
105	Timer switch 3 output	Output	R-CT	[1.1] DPT_Switch	1 bit
106	Timer switch 3 block	Input / Output	-WCT	[1.1] DPT_Switch	1 bit
107	Timer switch 4 output	Output	R-CT	[1.1] DPT_Switch	1 bit
108	Timer switch 4 block	Input / Output	-WCT	[1.1] DPT_Switch	1 bit
109	Timer switch 5 output	Output	R-CT	[1.1] DPT_Switch	1 bit
110	Timer switch 5 block	Input / Output	-WCT	[1.1] DPT_Switch	1 bit
111	Timer switch 6 output	Output	R-CT	[1.1] DPT_Switch	1 bit
112	Timer switch 6 block	Input / Output	-WCT	[1.1] DPT_Switch	1 bit

No.	Text	Function	Flags	DPT type	Size
113	Timer switch 7 output	Output	R-CT	[1.1] DPT_Switch	1 bit
114	Timer switch 7 block	Input / Output	-WCT	[1.1] DPT_Switch	1 bit
115	Timer switch 8 output	Output	R-CT	[1.1] DPT_Switch	1 bit
116	Timer switch 8 block	Input / Output	-WCT	[1.1] DPT_Switch	1 bit
121	Info page 1 Text 1	Input	-WT-	[16.0] DPT_String_ASCII	14 bytes
122	Info page 1 Text 2	Input	-WT-	[16.0] DPT_String_ASCII	14 bytes
123	Info page 2 Text 1	Input	-WT-	[16.0] DPT_String_ASCII	14 bytes
124	Info page 2 Text 2	Input	-WT-	[16.0] DPT_String_ASCII	14 bytes
<b>Tem</b> for a	<b>perature sensor</b> (objects 131-167) Il models				
131	Temperature sensor: Malfunction	Output	R-CT	[1.1] DPT_Switch	1 bit
132	Temperature sensor: Measured value external	Input	-WCT	[9.1] DPT_Val- ue_Temp	2 bytes
133	Temperature sensor: Measured value	Output	R-CT	[9.1] DPT_Val- ue_Temp	2 bytes
134	Temperature sensor: Measured value total	Output	R-CT	[9.1] DPT_Val- ue_Temp	2 bytes
135	Temperature sensor: Measured value min./max. query	Input	-WC-	[1.017] DPT_Trig- ger	1 bit
136	Temperature sensor: Minimum measured value	Output	R-CT	[9.1] DPT_Val- ue_Temp	2 bytes
137	Temperature sensor: Maximum measured value	Output	R-CT	[9.1] DPT_Val- ue_Temp	2 bytes
138	Temperature sensor: measured value min./max. reset	Input	-WC-	[1.017] DPT_Trig- ger	1 bit
141	Temp. threshold value 1: Absolute value	Input/ Output	RWCT	[9.1] DPT_Val- ue_Temp	2 bytes
142	Temp. threshold value 1: (1:+   0:-)	Input	-WC-	[1.1] DPT_Switch	1 bit
143	Temp. threshold value 1: Switching delay from 0 to 1	Input	-WC-	[7.005] DPT TimePeriodSec	2 bytes
144	Temp. threshold value 1: Switching delay from 1 to 0	Input	-WC-	[7.005] DPT TimePeriodSec	2 bytes
145	Temp. threshold value 1: Switching output	Output	R-CT	[1.1] DPT_Switch	1 bit
146	Temp. threshold value 1: Switching output block	Input	-WC-	[1.1] DPT_Switch	1 bit
148	Temp. threshold value 2: Absolute value	Input/ Output	RWCT	[9.1] DPT_Val- ue_Temp	2 bytes

No.	Text	Function	Flags	DPT type	Size
149	Temp. threshold value 2: (1:+   0:-)	Input	-WC-	[1.1] DPT_Switch	1 bit
150	Temp. threshold value 2: Switching delay from 0 to 1	Input	-WC-	[7.005] DPT TimePeriodSec	2 bytes
151	Temp. threshold value 2: Switching delay from 1 to 0	Input	-WC-	[7.005] DPT TimePeriodSec	2 bytes
152	Temp. threshold value 2: Switching output	Output	R-CT	[1.1] DPT_Switch	1 bit
153	Temp. threshold value 2: Switching output block	Input	-WC-	[1.1] DPT_Switch	1 bit
155	Temp. threshold value 3: Absolute value	Input/ Output	RWCT	[9.1] DPT_Val- ue_Temp	2 bytes
156	Temp. threshold value 3: (1:+   0:-)	Input	-WC-	[1.1] DPT_Switch	1 bit
157	Temp. threshold value 3: Switching delay from 0 to 1	Input	-WC-	[7.005] DPT TimePeriodSec	2 bytes
158	Temp. threshold value 3: Switching delay from 1 to 0	Input	-WC-	[7.005] DPT TimePeriodSec	2 bytes
159	Temp. threshold value 3: Switching output	Output	R-CT	[1.1] DPT_Switch	1 bit
160	Temp. threshold value 3: Switching output block	Input	-WC-	[1.1] DPT_Switch	1 bit
162	Temp. threshold value 4: Absolute value	Input/ Output	RWCT	[9.1] DPT_Val- ue_Temp	2 bytes
163	Temp. threshold value 4: (1:+   0:-)	Input	-WC-	[1.1] DPT_Switch	1 bit
164	Temp. threshold value 4: Switching delay from 0 to 1	Input	-WC-	[7.005] DPT TimePeriodSec	2 bytes
165	Temp. threshold value 4: Switching delay from 1 to 0	Input	-WC-	[7.005] DPT TimePeriodSec	2 bytes
166	Temp. threshold value 4: Switching output	Output	R-CT	[1.1] DPT_Switch	1 bit
167	Temp. threshold value 4: Switching output block	Input	-WC-	[1.1] DPT_Switch	1 bit
<b>Tem</b> for a	perature control (objects 171-205) Il models				
171	Temp. controller: HVAC mode (priority 1)	Input	-WC-	[20.102] DPT_H- VACMode	1 byte
172	Temp. controller: HVAC mode (priority 2)	Input	RWCT	[20.102] DPT_H- VACMode	1 byte
173	Temp. controller: Mode frost/heat protection activation	Input	RWCT	[1.1] DPT_Switch	1 bit
174	Temp. controller: Block (1 = Blocking)	Input	-WC-	[1.1] DPT_Switch	1 bit
175	Temp. controller: Current setpoint	Output	R-CT	[9.1] DPT_Val- ue_Temp	2 bytes

No.	Text	Function	Flags	DPT type	Size
176	Temp. controller: Switching (0: Heating   1: Cooling)	Input	-WC-	[1.1] DPT_Switch	1 bit
177	Temp. controller: Nominal value comfort heating	Input/ Output	RWCT	[9.1] DPT_Val- ue_Temp	2 bytes
178	Temp. controller: Nominal value comfort heating (1:+   0: -)	Input	-WC-	[1.1] DPT_Switch	1 bit
179	Temp. controller: Nominal value comfort cooling	Input/ Output	RWCT	[9.1] DPT_Val- ue_Temp	2 bytes
180	Temp. controller: Nominal value comfort cooling (1:+   0: -)	Input	-WC-	[1.1] DPT_Switch	1 bit
181	Temp. controller: Basic 16-bit setpoint shift	Input/ Output	RWCT	[9.1] DPT_Val- ue_Temp	2 bytes
182	Temp. controller: Nominal value standby heating	Input/ Output	RWCT	[9.1] DPT_Val- ue_Temp	2 bytes
183	Temp. controller: Nominal value standby heating (1:+   0: -)	Input	-WC-	[1.1] DPT_Switch	1 bit
184	Temp. controller: Nominal value standby cooling	Input/ Output	RWCT	[9.1] DPT_Val- ue_Temp	2 bytes
185	Temp. controller: Nominal value standby cooling (1:+   0: -)	Input	-WC-	[1.1] DPT_Switch	1 bit
186	Temp. controller: Nominal value eco heating	Input/ Output	RWCT	[9.1] DPT_Val- ue_Temp	2 bytes
187	Temp. controller: Nominal value eco heating (1:+   0: -)	Input	-WC-	[1.1] DPT_Switch	1 bit
188	Temp. controller: Nominal value eco cooling	Input/ Output	RWCT	[9.1] DPT_Val- ue_Temp	2 bytes
189	Temp. controller: Nominal value eco cooling (1:+   0: -)	Input	-WC-	[1.1] DPT_Switch	1 bit
190	Temp. controller: Act. variable, heating (level 1)	Output	R-CT	[5.1] DPT_Scaling	1 byte
191	Temp. controller: Act. variable, heating (level 2)	Output	R-CT	[5.1] DPT_Scaling	1 byte
192	Temp. controller: Act. variable cooling (level 1)	Output	R-CT	[5.1] DPT_Scaling	1 byte
193	Temp. controller: Act. variable cooling (level 2)	Output	R-CT	[5.1] DPT_Scaling	1 byte
194	Temperature controller Act. variable for 4/6-way valve	Output	R-CT	[5.1] DPT_Scaling	1 byte
195	Temp. controller: Status heating level 1 (1=ON   0=OFF)	Output	R-CT	[1.1] DPT_Switch	1 bit
196	Temp. controller: Status heating level 2 (1=ON   0=OFF)	Output	R-CT	[1.1] DPT_Switch	1 bit
197	Temp. controller: Status cooling level 1 (1=ON   0=OFF)	Output	R-CT	[1.1] DPT_Switch	1 bit

No.	Text	Function	Flags	DPT type	Size
198	Temp. controller: Status cooling level 2 (1=ON   0=OFF)	Output	R-CT	[1.1] DPT_Switch	1 bit
199	Temp. controller: Comfort extension status	Input/ Output	RWCT	[1.1] DPT_Switch	1 bit
200	Temp. controller: Comfort extension time	Input	RWCT	[7.005] DPT TimePeriodSec	2 bytes
201	Temp. Controller: Fan coil level 0 to 3	Output	R-CT	[5.1] DPT_Scaling	1 byte
202	Temp. Controller: Fan coil level 1	Output	R-CT	[1.1] DPT_Switch	1 bit
203	Temp. Controller: Fan coil level 2	Output	R-CT	[1.1] DPT_Switch	1 bit
204	Temp. Controller: Fan coil level 3	Output	R-CT	[1.1] DPT_Switch	1 bit
205	Temp. Controller: Fan coil auto=1 manual=0	Input / Output	RWCT	[1.1] DPT_Switch	1 bit
Sum	mer compensation (objects 209-211	)			
for a	I models		1		
209	Summer compensation: Outdoor temperature	Input	-WCT	[9.1] DPT_Val- ue_Temp	2 bytes
210	Summer compensation: Target value	Output	R-CT	[9.1] DPT_Val- ue_Temp	2 bytes
211	Summer compensation: Block (1 = Blocking)	Input	-WC-	[1.1] DPT_Switch	1 bit
Hum for C	<b>idity sensor</b> (objects 213-244) ala KNX AQS/TH (item no. 70613, 706	14), Cala KN	IX TH (it	em no. 70611, 7061	2),
213	Humidity sensor: Malfunction	Output	R-CT	[1.1] DPT_Switch	1 bit
214	Humidity sensor: External measured value	Input	-WCT	[9,007] DPT_Val- ue_Humidity	2 bytes
215	Humidity sensor: Measured value	Output	R-CT	[9,007] DPT_Val- ue_Humidity	2 bytes
216	Humidity sensor: Measured value total	Output	R-CT	[9,007] DPT_Val- ue_Humidity	2 bytes
217	Humidity sensor: Measured value min./max. query	Input	-WC-	[1.017] DPT_Trig- ger	1 bit
218	Humidity sensor: Minimum measured value	Output	R-CT	[9,007] DPT_Val- ue_Humidity	2 bytes
219	Humidity sensor: Maximum measured value	Output	R-CT	[9,007] DPT_Val- ue_Humidity	2 bytes
220	Humidity sensor: measured value min./max. reset	Input	-WC-	[1.017] DPT_Trig- ger	1 bit
221	Humidity threshold value 1: Absolute value	Input/ Output	RWCT	[9,007] DPT_Val- ue_Humidity	2 bytes
222	Humidity threshold value 1: (1:+   0:-)	Input	-WC-	[1.1] DPT_Switch	1 bit
223	Humidity threshold value 1: Delay from 0 to 1	Input	-WC-	[7.005] DPT TimePeriodSec	2 bytes

No.	Text	Function	Flags	DPT type	Size
224	Humidity threshold value 1: Delay from 1 to 0	Input	-WC-	[7.005] DPT TimePeriodSec	2 bytes
225	Humidity threshold value 1: Switching output	Output	R-CT	[1.1] DPT_Switch	1 bit
226	Humidity threshold value 1: Switching output block	Input	-WC-	[1.1] DPT_Switch	1 bit
227	Humidity threshold value 2: Absolute value	Input/ Output	RWCT	[9,007] DPT_Val- ue_Humidity	2 bytes
228	Humidity threshold value 2: (1:+   0:-)	Input	-WC-	[1.1] DPT_Switch	1 bit
229	Humidity threshold value 2: Delay from 0 to 1	Input	-WC-	[7.005] DPT TimePeriodSec	2 bytes
230	Humidity threshold value 2: Delay from 1 to 0	Input	-WC-	[7.005] DPT TimePeriodSec	2 bytes
231	Humidity threshold value 2: Switching output	Output	R-CT	[1.1] DPT_Switch	1 bit
232	Humidity threshold value 2: Switching output block	Input	-WC-	[1.1] DPT_Switch	1 bit
233	Humidity threshold value 3: Absolute value	Input/ Output	RWCT	[9,007] DPT_Val- ue_Humidity	2 bytes
234	Humidity threshold value 3: (1:+   0:-)	Input	-WC-	[1.1] DPT_Switch	1 bit
235	Humidity threshold value 3: Delay from 0 to 1	Input	-WC-	[7.005] DPT TimePeriodSec	2 bytes
236	Humidity threshold value 3: Delay from 1 to 0	Input	-WC-	[7.005] DPT TimePeriodSec	2 bytes
237	Humidity threshold value 3: Switching output	Output	R-CT	[1.1] DPT_Switch	1 bit
238	Humidity threshold value 3: Switching output block	Input	-WC-	[1.1] DPT_Switch	1 bit
239	Humidity threshold value 4: Absolute value	Input/ Output	RWCT	[9,007] DPT_Val- ue_Humidity	2 bytes
240	Humidity threshold value 4: (1:+   0:-)	Input	-WC-	[1.1] DPT_Switch	1 bit
241	Humidity threshold value 4: Delay from 0 to 1	Input	-WC-	[7.005] DPT TimePeriodSec	2 bytes
242	Humidity threshold value 4: Delay from 1 to 0	Input	-WC-	[7.005] DPT TimePeriodSec	2 bytes
243	Humidity threshold value 4: Switching output	Output	R-CT	[1.1] DPT_Switch	1 bit
244	Humidity threshold value 4: Switching output block	Input	-WC-	[1.1] DPT_Switch	1 bit
Dew for C	point, coolant monitoring (objects ala KNX AQS/TH (item no. 70613, 706	s 261-269) 14), Cala KN	IX TH (it	em no. 70611, 7061	2)
261	Dewpoint: Measured value	Output	R-CT	[9.1] DPT_Val- ue_Temp	2 bytes

No.	Text	Function	Flags	DPT type	Size
262	Coolant temp.: Threshold value	Output	R-CT	[9.1] DPT_Val- ue_Temp	2 bytes
263	Coolant temp.: Actual value	Input	RWCT	[9.1] DPT_Val- ue_Temp	2 bytes
264	Coolant temp.: Offset change (1:+   0:-)	Input	-WC-	[1.1] DPT_Switch	1 bit
265	Coolant temp.: Offset current	Output	R-CT	[9.1] DPT_Val- ue_Temp	2 bytes
266	Coolant temp.: Switching delay from 0 to 1	Input	-WC-	[7.005] DPT TimePeriodSec	2 bytes
267	Coolant temp.: Switching delay from 1 to 0	Input	-WC-	[7.005] DPT TimePeriodSec	2 bytes
268	Coolant temp.: Switching output	Output	R-CT	[1.1] DPT_Switch	1 bit
269	Coolant temp.: Switching output block	Input	-WC-	[1.1] DPT_Switch	1 bit
Abso	olute humidity (objects 271-272)				
for C	ala KNX AQS/TH (item no. 70613, 706	14), Cala KN	IX TH (it	em no. 70611, 7061	2)
271	Absolute humidity [g/kg]	Output	R-CT	[14.5] DPT_Val- ue_Amplitude	4 bytes
272	Absolute humidity [g/m <sup>3</sup> ]	Output	R-CT	[14.17] DPT_Val- ue_Density	4 bytes
<b>Roo</b> for C	<b>n climate status</b> (objects 274-275) ala KNX AQS/TH (item no. 70613, 706	14), Cala KN	IX TH (it	em no. 70611, 7061	2)
274	Ambient climate status: 1 = comfortable   0 = uncomfortable	Output	R-CT	[1.1] DPT_Switch	1 bit
275	Ambient climate status: Text	Output	R-CT	[16.0] DPT_String_ASCII	14 bytes
Hum	idity control (objects 291-299)				
for C	ala KNX AQS/TH (item no. 70613, 706	14), Cala KN	IX TH (it	em no. 70611, 7061	2)
291	Humidity controller: Block (1: block)	Input	-WC-	[1.2] DPT_Bool	1 bit
292	Humidity controller: Target value	Input/ Output	RWCT	[9,007] DPT_Val- ue_Humidity	2 bytes
293	Humidity controller: Target value (1:+   0:-)	Input	-WC-	[1.2] DPT_Bool	1 bit
294	Humidity controller: Act. variable dehumidification	Output	R-CT	[5.1] DPT_Scaling	1 byte
295	Humidity controller: Act. variable de-humidifying level 2	Output	R-CT	[5.1] DPT_Scaling	1 byte
296	Humidity controller: Act. variable humidification	Output	R-CT	[5.1] DPT_Scaling	1 byte
297	Humidity controller: Dehumidification status (1:ON   0:OFF)	Output	R-CT	[1.1] DPT_Switch	1 bit

No.	Text	Function	Flags	DPT type	Size
298	Humidity controller: Dehumidification 2 status (1:ON   0:OFF)	Output	R-CT	[1.1] DPT_Switch	1 bit
299	Humidity controller: Humidification status (1:ON   0:OFF)	Output	R-CT	[1.1] DPT_Switch	1 bit
<b>CO2</b> for C	<b>sensor</b> (objects 231-361) ala KNX AQS/TH (item no. 70613, 706	14)			
331	CO2 sensor: Malfunction	Output	R-CT	[1.1] DPT_Switch	1 bit
332	CO2 sensor: External measured value	Input	-WCT	[9,008] DPT_Val- ue_AirQuality	2 bytes
333	CO2 sensor: Measured value	Output	R-CT	[9,008] DPT_Val- ue_AirQuality	2 bytes
334	CO2 sensor: Measured value total	Output	R-CT	[9,008] DPT_Val- ue_AirQuality	2 bytes
335	CO2 sensor: Measured value max. query	Input	-WC-	[1.017] DPT_Trig- ger	1 bit
336	CO2 sensor: Maximum measured value	Output	R-CT	[9,008] DPT_Val- ue_AirQuality	2 bytes
337	CO2 sensor: Measured value max. reset	Input	-WC-	[1.017] DPT_Trig- ger	1 bit
338	CO2 threshold value 1: Absolute value	Input/ Output	RWCT	[9,008] DPT_Val- ue_AirQuality	2 bytes
339	CO2 threshold value 1: (1:+   0:-)	Input	-WC-	[1.1] DPT_Switch	1 bit
340	CO2 threshold value 1: Delay from 0 to 1	Input	-WC-	[7.005] DPT TimePeriodSec	2 bytes
341	CO2 threshold value 1: Delay from 1 to 0	Input	-WC-	[7.005] DPT TimePeriodSec	2 bytes
342	CO2 threshold value 1: Switching output	Output	R-CT	[1.1] DPT_Switch	1 bit
343	CO2 threshold value 1: Switching output block	Input	-WC-	[1.1] DPT_Switch	1 bit
344	CO2 threshold value 2: Absolute value	Input/ Output	RWCT	[9,008] DPT_Val- ue_AirQuality	2 bytes
345	CO2 threshold value 2: (1:+   0:-)	Input	-WC-	[1.1] DPT_Switch	1 bit
346	CO2 threshold value 2: Delay from 0 to 1	Input	-WC-	[7.005] DPT TimePeriodSec	2 bytes
347	CO2 threshold value 2: Delay from 1 to 0	Input	-WC-	[7.005] DPT TimePeriodSec	2 bytes
348	CO2 threshold value 2: Switching output	Output	R-CT	[1.1] DPT_Switch	1 bit
349	CO2 threshold value 2: Switching output block	Input	-WC-	[1.1] DPT_Switch	1 bit
350	CO2 threshold value 3: Absolute value	Input/ Output	RWCT	[9,008] DPT_Val- ue_AirQuality	2 bytes

No.	Text	Function	Flags	DPT type	Size
351	CO2 threshold value 3: (1:+   0:-)	Input	-WC-	[1.1] DPT_Switch	1 bit
352	CO2 threshold value 3: Delay from 0 to 1	Input	-WC-	[7.005] DPT TimePeriodSec	2 bytes
353	CO2 threshold value 3: Delay from 1 to 0	Input	-WC-	[7.005] DPT TimePeriodSec	2 bytes
354	CO2 threshold value 3: Switching output	Output	R-CT	[1.1] DPT_Switch	1 bit
355	CO2 threshold value 3: Switching output block	Input	-WC-	[1.1] DPT_Switch	1 bit
356	CO2 threshold value 4: Absolute value	Input/ Output	RWCT	[9,008] DPT_Val- ue_AirQuality	2 bytes
357	CO2 threshold value 4: (1:+   0:-)	Input	-WC-	[1.1] DPT_Switch	1 bit
358	CO2 threshold value 4: Delay from 0 to 1	Input	-WC-	[7.005] DPT TimePeriodSec	2 bytes
359	CO2 threshold value 4: Delay from 1 to 0	Input	-WC-	[7.005] DPT TimePeriodSec	2 bytes
360	CO2 threshold value 4: Switching output	Output	R-CT	[1.1] DPT_Switch	1 bit
361	CO2 threshold value 4: Switching output block	Input	-WC-	[1.1] DPT_Switch	1 bit
CO2	controller (objects 362-368)				
for C	ala KNX AQS/TH (item no. 70613, 706	14)	14/0		
362	CO2 controller: Block (1: block)	Input	-WC-		1 bit
363	CO2 controller: Target value	Input/ Output	RWCI	[9,008] DP1_Val- ue_AirQuality	2 bytes
364	CO2 controller: Target value (1:+   0:-)	Input	-WC-	[1.2] DPT_Bool	1 bit
365	CO2 controller: Act. variable ventilation	Output	R-CT	[5.1] DPT_Scaling	1 byte
366	CO2 controller: Act. variable ventilation level 2	Output	R-CT	[5.1] DPT_Scaling	1 byte
367	CO2 controller: Ventilation status (1:ON   0:OFF)	Output	R-CT	[1.1] DPT_Switch	1 bit
368	CO2 controller: Status ventilation level 2 (1=ON   0=OFF)	Output	R-CT	[1.1] DPT_Switch	1 bit
Act.	variable comparator (objects 401-4	28)			
for a	ll models			1	1
401	Comparator 1 actuating variable: Input 1	Input	-WC-	[5.1] DPT_Scaling	1 byte
402	Comparator 1 actuating variable: Input 2	Input	-WC-	[5.1] DPT_Scaling	1 byte
403	Comparator 1 actuating variable: Input 3	Input	-WC-	[5.1] DPT_Scaling	1 byte

No.	Text	Function	Flags	DPT type	Size
404	Comparator 1 actuating variable: Input 4	Input	-WC-	[5.1] DPT_Scaling	1 byte
405	Comparator 1 actuating variable: Input 5	Input	-WC-	[5.1] DPT_Scaling	1 byte
406	Comparator 1 actuating variable: Output	Output	R-CT	[5.1] DPT_Scaling	1 byte
407	Comparator 1 actuating variable: Block (1: block)	Output	-WC-	[1.2] DPT_Bool	1 bit
408	Comparator 2 actuating variable: Input 1	Input	-WC-	[5.1] DPT_Scaling	1 byte
409	Comparator 2 actuating variable: Input 2	Input	-WC-	[5.1] DPT_Scaling	1 byte
410	Comparator 2 actuating variable: Input 3	Input	-WC-	[5.1] DPT_Scaling	1 byte
411	Comparator 2 actuating variable: Input 4	Input	-WC-	[5.1] DPT_Scaling	1 byte
412	Comparator 2 actuating variable: Input 5	Input	-WC-	[5.1] DPT_Scaling	1 byte
413	Comparator 2 actuating variable: Output	Output	R-CT	[5.1] DPT_Scaling	1 byte
414	Comparator 2 actuating variable: Block (1: block)	Output	-WC-	[1.2] DPT_Bool	1 bit
415	Comparator 3 actuating variable: Input 1	Input	-WC-	[5.1] DPT_Scaling	1 byte
416	Comparator 3 actuating variable: Input 2	Input	-WC-	[5.1] DPT_Scaling	1 byte
417	Comparator 3 actuating variable: Input 3	Input	-WC-	[5.1] DPT_Scaling	1 byte
418	Comparator 3 actuating variable: Input 4	Input	-WC-	[5.1] DPT_Scaling	1 byte
419	Comparator 3 actuating variable: Input 5	Input	-WC-	[5.1] DPT_Scaling	1 byte
420	Comparator 3 actuating variable: Output	Output	R-CT	[5.1] DPT_Scaling	1 byte
421	Comparator 3 actuating variable: Block (1: block)	Output	-WC-	[1.2] DPT_Bool	1 bit
422	Comparator 4 actuating variable: Input 1	Input	-WC-	[5.1] DPT_Scaling	1 byte
423	Comparator 4 actuating variable: Input 2	Input	-WC-	[5.1] DPT_Scaling	1 byte
424	Comparator 4 actuating variable: Input 3	Input	-WC-	[5.1] DPT_Scaling	1 byte
425	Comparator 4 actuating variable: Input 4	Input	-WC-	[5.1] DPT_Scaling	1 byte

No.	Text	Function	Flags	DPT type	Size
426	Comparator 4 actuating variable: Input 5	Input	-WC-	[5.1] DPT_Scaling	1 byte
427	Comparator 4 actuating variable: Output	Output	R-CT	[5.1] DPT_Scaling	1 byte
428	Comparator 4 actuating variable: Block (1: block)	Output	-WC-	[1.2] DPT_Bool	1 bit
Com	puter (multi-function modules) (o	bjects 441-5	504)		
for a	ll models	1		1	
441	Computer 1: Input I1	Input	RWCT	Depending on setting	4 bytes
442	Computer 1: Input I2	Input	RWCT	Depending on setting	4 bytes
443	Computer 1: Input I3	Input	RWCT	Depending on setting	4 bytes
444	Computer 1: Output O1	Output	R-CT	Depending on setting	4 bytes
445	Computer 1: Output O2	Output	R-CT	Depending on setting	4 bytes
446	Computer 1: Condition text	Output	R-CT	[16.0] DPT_String_ASCII	14 bytes
447	Computer 1: Monitoring status	Output	R-CT	[1.1] DPT_Switch	1 bit
448	Computer 1: Block (1: block)	Input	-WC-	[1.1] DPT_Switch	1 bit
449	Computer 2: Input I1	Input	RWCT	Depending on setting	4 bytes
450	Computer 2: Input I2	Input	RWCT	Depending on setting	4 bytes
451	Computer 2: Input I3	Input	RWCT	Depending on setting	4 bytes
452	Computer 2: Output O1	Output	R-CT	Depending on setting	4 bytes
453	Computer 2: Output O2	Output	R-CT	Depending on setting	4 bytes
454	Computer 2: Condition text	Output	R-CT	[16.0] DPT_String_ASCII	14 bytes
455	Computer 2: Monitoring status	Output	R-CT	[1.1] DPT_Switch	1 bit
416	Computer 2: Block (1: block)	Input	-WC-	[1.1] DPT_Switch	1 bit
457	Computer 3: Input I1	Input	RWCT	Depending on setting	4 bytes
458	Computer 3: Input I2	Input	RWCT	Depending on setting	4 bytes
459	Computer 3: Input I3	Input	RWCT	Depending on setting	4 bytes
460	Computer 3: Output O1	Output	R-CT	Depending on setting	4 bytes

No.	Text	Function	Flags	DPT type	Size
461	Computer 3: Output O2	Output	R-CT	Depending on setting	4 bytes
462	Computer 3: Condition text	Output	R-CT	[16.0] DPT_String_ASCII	14 bytes
463	Computer 3: Monitoring status	Output	R-CT	[1.1] DPT_Switch	1 bit
464	Computer 3: Block (1: block)	Input	-WC-	[1.1] DPT_Switch	1 bit
465	Computer 4: Input I1	Input	RWCT	Depending on setting	4 bytes
466	Computer 4: Input I2	Input	RWCT	Depending on setting	4 bytes
467	Computer 4: Input I3	Input	RWCT	Depending on setting	4 bytes
468	Computer 4: Output O1	Output	R-CT	Depending on setting	4 bytes
469	Computer 4: Output O2	Output	R-CT	Depending on setting	4 bytes
470	Computer 4: Condition text	Output	R-CT	[16.0] DPT_String_ASCII	14 bytes
471	Computer 4: Monitoring status	Output	R-CT	[1.1] DPT_Switch	1 bit
472	Computer 4: Block (1: block)	Input	-WC-	[1.1] DPT_Switch	1 bit
473	Computer 5: Input I1	Input	RWCT	Depending on setting	4 bytes
474	Computer 5: Input I2	Input	RWCT	Depending on setting	4 bytes
475	Computer 5: Input I3	Input	RWCT	Depending on setting	4 bytes
476	Computer 5: Output O1	Output	R-CT	Depending on setting	4 bytes
477	Computer 5: Output O2	Output	R-CT	Depending on setting	4 bytes
478	Computer 5: Condition text	Output	R-CT	[16.0] DPT_String_ASCII	14 bytes
479	Computer 5: Monitoring status	Output	R-CT	[1.1] DPT_Switch	1 bit
480	Computer 5: Block (1: block)	Input	-WC-	[1.1] DPT_Switch	1 bit
481	Computer 6: Input I1	Input	RWCT	Depending on setting	4 bytes
482	Computer 6: Input I2	Input	RWCT	Depending on setting	4 bytes
483	Computer 6: Input I3	Input	RWCT	Depending on setting	4 bytes
484	Computer 6: Output O1	Output	R-CT	Depending on setting	4 bytes
485	Computer 6: Output O2	Output	R-CT	Depending on setting	4 bytes

No.	Text	Function	Flags	DPT type	Size
486	Computer 6: Condition text	Output	R-CT	[16.0] DPT_String_ASCII	14 bytes
487	Computer 6: Monitoring status	Output	R-CT	[1.1] DPT_Switch	1 bit
488	Computer 6: Block (1: block)	Input	-WC-	[1.1] DPT_Switch	1 bit
489	Computer 7: Input I1	Input	RWCT	Depending on setting	4 bytes
490	Computer 7: Input I2	Input	RWCT	Depending on setting	4 bytes
491	Computer 7: Input I3	Input	RWCT	Depending on setting	4 bytes
492	Computer 7: Output O1	Output	R-CT	Depending on setting	4 bytes
493	Computer 7: Output O2	Output	R-CT	Depending on setting	4 bytes
494	Computer 7: Condition text	Output	R-CT	[16.0] DPT_String_ASCII	14 bytes
495	Computer 7: Monitoring status	Output	R-CT	[1.1] DPT_Switch	1 bit
496	Computer 7: Block (1: block)	Input	-WC-	[1.1] DPT_Switch	1 bit
497	Computer 8: Input I1	Input	RWCT	Depending on setting	4 bytes
498	Computer 8: Input I2	Input	RWCT	Depending on setting	4 bytes
499	Computer 8: Input I3	Input	RWCT	Depending on setting	4 bytes
500	Computer 8: Output O1	Output	R-CT	Depending on setting	4 bytes
501	Computer 8: Output O2	Output	R-CT	Depending on setting	4 bytes
502	Computer 8: Condition text	Output	R-CT	[16.0] DPT_String_ASCII	14 bytes
503	Computer 8: Monitoring status	Output	R-CT	[1.1] DPT_Switch	1 bit
504	Computer 8: Block (1: block)	Input	-WC-	[1.1] DPT_Switch	1 bit
<b>Logi</b> for a	<b>c</b> (objects 521-604) Il models				
521	Logic input 1	Input	-WC-	[1.2] DPT_Bool	1 bit
522	Logic input 2	Input	-WC-	[1.2] DPT_Bool	1 bit
523	Logic input 3	Input	-WC-	[1.2] DPT_Bool	1 bit
524	Logic input 4	Input	-WC-	[1.2] DPT_Bool	1 bit
525	Logic input 5	Input	-WC-	[1.2] DPT_Bool	1 bit
526	Logic input 6	Input	-WC-	[1.2] DPT_Bool	1 bit
527	Logic input 7	Input	-WC-	[1.2] DPT_Bool	1 bit
528	Logic input 8	Input	-WC-	[1.2] DPT_Bool	1 bit
529	Logic input 9	Input	-WC-	[1.2] DPT_Bool	1 bit

Room Controller Cala Touch KNX • Version: 28.04.2020 • Technical changes and errors excepted.

No.	Text	Function	Flags	DPT type	Size
530	Logic input 10	Input	-WC-	[1.2] DPT_Bool	1 bit
531	Logic input 11	Input	-WC-	[1.2] DPT_Bool	1 bit
532	Logic input 12	Input	-WC-	[1.2] DPT_Bool	1 bit
533	Logic input 13	Input	-WC-	[1.2] DPT_Bool	1 bit
534	Logic input 14	Input	-WC-	[1.2] DPT_Bool	1 bit
535	Logic input 15	Input	-WC-	[1.2] DPT_Bool	1 bit
536	Logic input 16	Input	-WC-	[1.2] DPT_Bool	1 bit
541	AND logic 1: 1-bit switching output	Output	R-CT	[1.2] DPT_Bool	1 bit
542	AND logic 1: 8-bit output A	Output	R-CT	[5.010] DPT_Val- ue_1_Ucount	1 byte
543	AND logic 1: 8-bit output B	Output	R-CT	[5.010] DPT_Val- ue_1_Ucount	1 byte
544	AND logic 1: Block	Input	-WC-	[1.1] DPT_Switch	1 bit
545	AND logic 2: 1-bit switching output	Output	R-CT	[1.2] DPT_Bool	1 bit
546	AND logic 2: 8-bit output A	Output	R-CT	[5.010] DPT_Val- ue_1_Ucount	1 byte
547	AND logic 2: 8-bit output B	Output	R-CT	[5.010] DPT_Val- ue_1_Ucount	1 byte
548	AND logic 2: Block	Input	-WC-	[1.1] DPT_Switch	1 bit
549	AND logic 3: 1-bit switching output	Output	R-CT	[1.2] DPT_Bool	1 bit
550	AND logic 3: 8-bit output A	Output	R-CT	[5.010] DPT_Val- ue_1_Ucount	1 byte
551	AND logic 3: 8-bit output B	Output	R-CT	[5.010] DPT_Val- ue_1_Ucount	1 byte
552	AND logic 3: Block	Input	-WC-	[1.1] DPT_Switch	1 bit
553	AND logic 4: 1-bit switching output	Output	R-CT	[1.2] DPT_Bool	1 bit
554	AND logic 4: 8-bit output A	Output	R-CT	[5.010] DPT_Val- ue_1_Ucount	1 byte
555	AND logic 4: 8-bit output B	Output	R-CT	[5.010] DPT_Val- ue_1_Ucount	1 byte
556	AND logic 4: Block	Input	-WC-	[1.1] DPT_Switch	1 bit
557	AND logic 5: 1-bit switching output	Output	R-CT	[1.2] DPT_Bool	1 bit
558	AND logic 5: 8-bit output A	Output	R-CT	[5.010] DPT_Val- ue_1_Ucount	1 byte
559	AND logic 5: 8-bit output B	Output	R-CT	[5.010] DPT_Val- ue_1_Ucount	1 byte
560	AND logic 5: Block	Input	-WC-	[1.1] DPT_Switch	1 bit
561	AND logic 6: 1-bit switching output	Output	R-CT	[1.2] DPT_Bool	1 bit
562	AND logic 6: 8-bit output A	Output	R-CT	[5.010] DPT_Val- ue_1_Ucount	1 byte
563	AND logic 6: 8-bit output B	Output	R-CT	[5.010] DPT_Val- ue_1_Ucount	1 byte

No.	Text	Function	Flags	DPT type	Size
564	AND logic 6: Block	Input	-WC-	[1.1] DPT_Switch	1 bit
565	AND logic 7: 1-bit switching output	Output	R-CT	[1.2] DPT_Bool	1 bit
566	AND logic 7: 8-bit output A	Output	R-CT	[5.010] DPT_Val-	1 byte
				ue_1_Ucount	
567	AND logic 7: 8-bit output B	Output	R-CT	[5.010] DPT_Val- ue_1_Ucount	1 byte
568	AND logic 7: Block	Input	-WC-	[1.1] DPT_Switch	1 bit
569	AND logic 8: 1-bit switching output	Output	R-CT	[1.2] DPT_Bool	1 bit
570	AND logic 8: 8-bit output A	Output	R-CT	[5.010] DPT_Val- ue_1_Ucount	1 byte
571	AND logic 8: 8-bit output B	Output	R-CT	[5.010] DPT_Val- ue_1_Ucount	1 byte
572	AND logic 8: Block	Input	-WC-	[1.1] DPT_Switch	1 bit
573	OR logic 1: 1-bit switching output	Output	R-CT	[1.2] DPT_Bool	1 bit
574	OR logic 1: 8-bit output A	Output	R-CT	[5.010] DPT_Val- ue_1_Ucount	1 byte
575	OR logic 1: 8-bit output B	Output	R-CT	[5.010] DPT_Val- ue_1_Ucount	1 byte
576	OR logic 1: Block	Input	-WC-	[1.1] DPT_Switch	1 bit
577	OR logic 2: 1-bit switching output	Output	R-CT	[1.2] DPT_Bool	1 bit
578	OR logic 2: 8-bit output A	Output	R-CT	[5.010] DPT_Val- ue_1_Ucount	1 byte
579	OR logic 2: 8-bit output B	Output	R-CT	[5.010] DPT_Val- ue_1_Ucount	1 byte
580	OR logic 2: Block	Input	-WC-	[1.1] DPT_Switch	1 bit
581	OR logic 3: 1-bit switching output	Output	R-CT	[1.2] DPT_Bool	1 bit
582	OR logic 3: 8-bit output A	Output	R-CT	[5.010] DPT_Val- ue 1 Ucount	1 byte
583	OR logic 3: 8-bit output B	Output	R-CT	[5.010] DPT_Val- ue 1 Ucount	1 byte
584	OR logic 3: Block	Input	-WC-	[1.1] DPT_Switch	1 bit
585	OR logic 4: 1-bit switching output	Output	R-CT	[1.2] DPT_Bool	1 bit
586	OR logic 4: 8-bit output A	Output	R-CT	[5.010] DPT_Val- ue 1 Ucount	1 byte
587	OR logic 4: 8-bit output B	Output	R-CT	[5.010] DPT_Val- ue_1_Ucount0	1 byte
588	OR logic 4: Block	Input	-WC-	[1.1] DPT_Switch	1 bit
589	OR logic 5: 1-bit switching output	Output	R-CT	[1.2] DPT_Bool	1 bit
590	OR logic 5: 8-bit output A	Output	R-CT	[5.010] DPT_Val- ue_1_Ucount	1 byte
591	OR logic 5: 8-bit output B	Output	R-CT	[5.010] DPT_Val- ue_1_Ucount	1 byte
592	OR logic 5: Block	Input	-WC-	[1.1] DPT_Switch	1 bit

No.	Text	Function	Flags	DPT type	Size
593	OR logic 6: 1-bit switching output	Output	R-CT	[1.2] DPT_Bool	1 bit
594	OR logic 6: 8-bit output A	Output	R-CT	[5.010] DPT_Val-	1 byte
				ue_1_Ucount	
595	OR logic 6: 8-bit output B	Output	R-CT	[5.010] DPT_Val-	1 byte
				ue_1_Ucount	
596	OR logic 6: Block	Input	-WC-	[1.1] DPT_Switch	1 bit
597	OR logic 7: 1-bit switching output	Output	R-CT	[1.2] DPT_Bool	1 bit
598	OR logic 7: 8-bit output A	Output	R-CT	[5.010] DPT_Val- ue_1_Ucount	1 byte
599	OR logic 7: 8-bit output B	Output	R-CT	[5.010] DPT_Val- ue_1_Ucount	1 byte
600	OR logic 7: Block	Input	-WC-	[1.1] DPT_Switch	1 bit
601	OR logic 8: 1-bit switching output	Output	R-CT	[1.2] DPT_Bool	1 bit
602	OR logic 8: 8-bit output A	Output	R-CT	[5.010] DPT_Val- ue_1_Ucount	1 byte
603	OR logic 8: 8-bit output B	Output	R-CT	[5.010] DPT_Val- ue_1_Ucount	1 byte
604	OR logic 8: Block	Input	-WC-	[1.1] DPT_Switch	1 bit
<b>Inpu</b> for a	<b>ts</b> (objects 621-664) Il models				
621	Push-button 1 long-term	Output	R-CT	[1.8] DPT_Up- Down	1 bit
622	Push-button 1 short-term	Output	R-CT	[1.10] DPT_Start	1 bit
623	Push-button 1 switching	Output	R-CT	[1.1] DPT_Switch	1 bit
624	Push button 1 dimming	Input/ Output	RWCT	[3.7] DPT_Con- trol_Dimming	4 bit
625	Push-button 1 encoder 8 bit	Output	R-CT	[5.10] DPT_Val- ue_1_Ucount	1 byte
626	Push-button 1 encoder 16 bit	Output	R-CT	[9] 9.xxx	2 bytes
627	Button 1 Scene (call up)	Output	R-CT	[18,001] DPT_SceneCon- trol	1 byte
628	Button 1 NTC measured value	Output	R-CT	[9.1] DPT_Val- ue_Temp	2 bytes
629	Button 1 NTC external measured value	Input	-WC-	[9.1] DPT_Val- ue_Temp	2 bytes
630	Button 1 NTC total measured value	Output	R-CT	[9.1] DPT_Val- ue_Temp	2 bytes
631	Button 1 NTC malfunction	Output	R-CT	[1.1] DPT_Switch	1 bit
632	Push-button 2 long-term	Output	R-CT	[1.8] DPT_Up- Down	1 bit
633	Push-button 2 short-term	Output	R-CT	[1.10] DPT_Start	1 bit
634	Push-button 2 switching	Output	R-CT	[1.1] DPT_Switch	1 bit

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No.	Text	Function	Flags	DPT type	Size
635	Push button 2 dimming	Input/ Output	RWCT	[3.7] DPT_Con- trol_Dimming	4 bit
636	Push-button 2 encoder 8 bit	Output	R-CT	[5.10] DPT_Val- ue_1_Ucount	1 byte
637	Push-button 2 encoder 16 bit	Output	R-CT	[9] 9.xxx	2 bytes
638	Button 2 Scene (call up)	Output	R-CT	[18,001] DPT_SceneCon- trol	1 byte
639	Button 2 NTC measured value	Output	R-CT	[9.1] DPT_Val- ue_Temp	2 bytes
630	Button 2 NTC external measured value	Input	-WC-	[9.1] DPT_Val- ue_Temp	2 bytes
641	Button 2 NTC total measured value	Output	R-CT	[9.1] DPT_Val- ue_Temp	2 bytes
642	Button 2 NTC malfunction	Output	R-CT	[1.1] DPT_Switch	1 bit
643	Push-button 3 long-term	Output	R-CT	[1.8] DPT_Up- Down	1 bit
644	Push-button 3 short-term	Output	R-CT	[1.10] DPT_Start	1 bit
645	Push-button 3 switching	Output	R-CT	[1.1] DPT_Switch	1 bit
646	Push button 3 dimming	Input/ Output	RWCT	[3.7] DPT_Con- trol_Dimming	4 bit
647	Push-button 3 encoder 8 bit	Output	R-CT	[5.10] DPT_Val- ue_1_Ucount	1 byte
648	Push-button 3 encoder 16 bit	Output	R-CT	[9] 9.xxx	2 bytes
649	Button 3 Scene (call up)	Output	R-CT	[18,001] DPT_SceneCon- trol	1 byte
650	Button 3 NTC measured value	Output	R-CT	[9.1] DPT_Val- ue_Temp	2 bytes
651	Button 3 NTC external measured value	Input	-WC-	[9.1] DPT_Val- ue_Temp	2 bytes
652	Button 3 NTC total measured value	Output	R-CT	[9.1] DPT_Val- ue_Temp	2 bytes
653	Button 3 NTC malfunction	Output	R-CT	[1.1] DPT_Switch	1 bit
654	Push-button 4 long-term	Output	R-CT	[1.8] DPT_Up- Down	1 bit
655	Push-button 4 short-term	Output	R-CT	[1.10] DPT_Start	1 bit
656	Push-button 4 switching	Output	R-CT	[1.1] DPT_Switch	1 bit
657	Push button 4 dimming	Input/ Output	RWCT	[3.7] DPT_Con- trol_Dimming	4 bit
658	Push-button 4 encoder 8 bit	Output	R-CT	[5.10] DPT_Val- ue_1_Ucount	1 byte
659	Push-button 4 encoder 16 bit	Output	R-CT	[9] 9.xxx	2 bytes

No.	Text	Function	Flags	DPT type	Size
660	Button 4 Scene (call up)	Output	R-CT	[18,001] DPT_SceneCon- trol	1 byte
661	Button 4 NTC measured value	Output	R-CT	[9.1] DPT_Val- ue_Temp	2 bytes
662	Button 4 NTC external measured value	Input	-WC-	[9.1] DPT_Val- ue_Temp	2 bytes
663	Button 4 NTC total measured value	Output	R-CT	[9.1] DPT_Val- ue_Temp	2 bytes
664	Button 4 NTC malfunction	Output	R-CT	[1.1] DPT_Switch	1 bit

# 7. Setting the parameters and functions for all models

The parameters are the same for all device models. Individual deviations are indicated in the text.

# 7.1. Behaviour on power failure/ restoration of power

#### Behaviour following a failure of the bus power supply:

The device sends nothing.

#### Behaviour on bus restoration of power and following programming or reset:

The device sends all outputs according to their send behaviour set in the parameters with the delays established in the "General settings" parameter block.

### 7.2. General settings

Set basic characteristics for the data transfer. A different transmission delay prevents an overload of the bus shortly after the reset.

In addition set whether the time and date are to be received as separate objects or as one common object. If time and date are received via two objects , then only a maximum of 10 seconds may elapse between receiving the date and receiving the time. Furthermore, a change of date may not occur between receiving both objects. The objects must be received by the device on the same day.

Transmission delay in seconds after reset/res	storation of bus for:
Measured values	<u>5</u> 300
Threshold values and switching outputs	<u>5</u> 300
Controller objects	<u>5</u> 300
Comparator and computer objects	<u>5</u> 300
Logic objects	<u>5</u> 300
Interface objects	<u>5</u> 300
Menu objects	<u>5</u> 300
Object type date and time	<ul> <li>two separate objects</li> </ul>
	<ul> <li>one common object</li> </ul>
Maximum telegram rate	1 • 2 • 5 • <u>10</u> • 20 • 50
	Telegrams per second

# 7.3. Display

The start page, screen save, brightness and language may be set for the display of the **Room Controller Cala Touch KNX**. Display settings can be modified via objects, in the ETS menu or on the display.

#### **Object control**

For the settings via objects, i.e. via the bus, objects 25-30 are available. Activate the object controls as desired.

Use screen objects	• <u>No</u>
	• Yes

#### ETS

Set whether and/or when the ETS screen settings are to remain active. Do not use the setting "after power restoration and programming" for first commissioning.

The following parameters should be maintained	not <u>after power restoration</u>
	<ul> <li>after power restoration and programming</li> </ul>

Adjust the wait time for the screen saver and for jumping back to the start page. Screen saver and switch to start page can be switched off below.

Screen saver wait time in seconds	12700; <u>300</u>
No touch wait time in seconds for switch to start page	12700; <u>60</u>

Adjust the language and display brightness You may choose between German and English as display languages.

Language	German [de] object value: 25701     English [en] object value: 25966
Brightness in %	1 <u>100</u>

Select the type of screen saver (clock or black screen) or deactivate the screen saver ("inactive"). When displaying the date and time, you can also select whether the indoor and outdoor temperatures are to be displayed alternately.

Then select whether the display is to jump to the start page if the screen is not touched for a certain period of time.

Screen saver type	inactive • date and time • screen off
Content of screen saver	<ul> <li><u>only date and time</u></li> <li>Date+time, indoor/outdoor temperature</li> </ul>
Switch to start page if no touch	No ● <u>Yes</u>

Menu start page	• Settings
Wend Start page	• Conservations
	• Sensor system
	<ul> <li>Temperature controller</li> </ul>
	• Light 1
	• Light 2
	• Light 3
	Drive 1
	• Drive 2
	• Drive 3
	Scenes
	<ul> <li>Universal functions</li> </ul>
	RGB control
	Color temperature
	HCL control
	Timer switch
	• Info page 1
	• Info page 2

Select the menu page to be displayed as the start page.

#### Display

The possible settings on the device display are explained in the chapter *Device control* on the touch display > Device settings, page 14.

# 7.4. Button tone

The **Room Controller Cala Touch KNX** may output an acoustic signal as feedback if a key on the screen is activated. The button tone may be switched on or off via an object, in the ETS menu or on the display.

#### **Object control**

Settings via an object, i.e. via the bus, is executed with object 31 (1 = On, 0 = Off). Activate the object controls as desired.

Use button tone object <u>No</u> •	• Yes
------------------------------------	-------

#### ETS

Set whether and/or when the ETS settings for the button tone are to remain active. Do not use the setting "after voltage return and programming" for first commissioning.

The following parameters	never be retained
should be maintained	<ul> <li>after power restoration</li> </ul>
	<ul> <li>after power restoration and</li> </ul>
	programming

Switch the tone on or off.

#### Display

The possible settings on the device display are explained in the chapter *Device control* on the touch display Device settings > Button tone, page 18.

## 7.5. Menus

The **Room Controller Cala Touch KNX** may show display setting pages, sensor values and various user interface areas. This is where you select the menus the user can see. The user can call up the different menus on the display by swiping to the right or left.

If the menus for the control of the temperature, for light or drives, additional settings appear in the application.

Use the following menus	
Settings	No • <u>Yes</u>
Sensor system	No • <u>Yes</u>
Temperature control	<u>No</u> •Yes
Light 1	<u>No</u> •Yes
Light 2	<u>No</u> •Yes
Light 3	<u>No</u> •Yes
Drive 1	<u>No</u> •Yes
Drive 2	<u>No</u> • Yes
Drive 3	<u>No</u> •Yes
Scenes	<u>No</u> •Yes
Universal display	<u>No</u> • Yes
RGB control	<u>No</u> • Yes
Color temperature	<u>No</u> • Yes
HCL control	<u>No</u> • Yes
Timer switch	<u>No</u> •Yes
Info page 1	<u>No</u> •Yes
Info page 2	<u>No</u> •Yes

The "Settings" menu and the control options on the device display are explained in chapter *Operating the device via the touch display*, page 12.

#### 7.5.1. Settings

These display pages allow setting the screen and button tone and show the device version.

The possible settings on the device display are explained in the chapter *Device control* on the touch display > Device settings, page 14.

#### 7.5.2. Sensor system

The display page "Sensor system" shows the sensor measured values.

The possible appearance settings on the device display are explained in the chapter *Device control on the touch display > Sensor system (measured value display)*, page 19.

#### 7.5.3. Temperature control



# The temperature control menu is connected with the internal temperature PI control of the device!

In order to show the temperature control menu, the temperature PI control of the device must be activated.

This sub-item of the application determines the name of the menu and the functions shown.

Insert the name to be shown on the menu page.

Name

[free text]

Decide whether the control mode is to be manually modified and if so, which modes may be selected.

Allow mode selection	<u>No</u> •Yes
The following modes may be activated from the menu.	
Comfort	No • <u>Yes</u>
Comfort extension	No • <u>Yes</u>
Standby	No • <u>Yes</u>
Eco	No • <u>Yes</u>
Protection	<u>No</u> •Yes

Then determine the nominal values on the display that may be modified. The nominal values may only be modified for the mode that is currently active.

The following nominal values can be set in the current mode	
Comfort	No • <u>Yes</u>
Standby	No • <u>Yes</u>
Eco	No • <u>Yes</u>
Protection	No (cannot be modified)

Activate the fan coil control if a heating/cooling unit with blower is to be controlled. Then the fan speed of convectors can be adjusted manually or via the corresponding actuating variable.

Level 0: actuating variable: 0% Level 1: actuating variable: 1...33% Level 2: actuating variable: 34...66% Level 3: actuating variable: 67...100% When used as a controller extension unit, the following additional parameters can be set (see also *Temperature PI control – Controller extension unit*, page 98):

Read controller information after	560; <u>10</u> seconds the latest
Changing and transmitting nominal values when operating the +/- keys	<u>No</u> • Yes
Increment for changing nominal value [only if nominal values are changed during operation]	150; <u>5</u> in 0,1°C

The possible settings on the device display are explained in the chapter *Device control* on the touch display > Temperature control, page 21.

#### 7.5.4. Light 1-3

The interface can be adapted to the light to be switched or dimmed for every light control menu, and you can select a symbol.

Insert the name to be shown on the menu page.

Determine the type of control, i.e. whether the lamp is to be switched via one or two areas and whether the lamp can be dimmed.

Type of control	<ul> <li><u>one area (off/on) switchable</u></li> <li>one area (on(off) switchable and dimmable</li> <li>two areas (left off/right on) switchable</li> <li>two areas (left off/right on)</li> </ul>
	switchable+dimmable

Select the symbol shown.

Symbol	Circle • Light bulb
--------	---------------------

For all control types with dimming, select weather the current brightness value shall be displayed. Also determine the period of time between switching and dimming. Short tapping means a switch command. If the finger rests on the area for longer than the set time, dimming is initiated.

The dimming command can also be repeated, i.e. it is dimmed another level when the area is touched for another interval. The dimming level per repetition/interval can also be set.

Display brightness value	<u>No</u> • Yes
Time between switching and dimming in 0.1 sec.	250; <u>5</u>
Repetition of the dimming command	<u>No</u> • Yes

Repetition of the dimming command for long key activation in 0.1 sec. [when the dimming command is repeated]	250; <u>5</u>
Dimming by [when the dimming command is repeated]	100.00% • 50.00% • 25.00% • <u>12.50%</u> • 6.25% • 3.13% • 1.56%

The possible settings on the device display are explained in the chapter *Device control* on the touch display > Light, page 22.

#### 7.5.5. Drive 1-3

The key reaction for the drive to be utilised can be adjusted for each drive operation menu.

Insert the name to be shown on the menu page.

Name	[free text]
------	-------------

Determine the function, i.e. the type of drive.

Function	<ul> <li>Shutter</li> <li><u>Blinds</u></li> <li>Awning</li> <li>Window</li> </ul>
Swap UP/DOWN [blind, shutter] Swap RETRACT/EXTEND [awning] Swap OPEN/CLOSE [window]	<u>No</u> •Yes

Set whether a slider should be displayed for operation and whether the current movement position should be displayed in percent.

Use slide bar for movement position	<u>No</u> • Yes
Use slide bar for slat position [blind only]	<u>No</u> • Yes
Invert slide bar	<u>No</u> • Yes
Display movement position	<u>No</u> • Yes
Display slat position [blind only]	<u>No</u> • Yes

Select the mode for the touch keys. Depending on the mode, various other parameters must be set.

Mode	<ul> <li>Standard</li> <li>Standard inverted</li> </ul>
	<ul><li>Comfort mode</li><li>Dead man's switch</li></ul>

The other setting options correspond to those of the interface inputs. For this observe chapter *Control modes for drive control*, page 82.

If necessary, activate and configure the operation block of the drive. This allows other functions in the KNX system to block manual operation, for example a protective function.

Use block	<u>No</u> • Yes
Blocking object evaluation	$\frac{1 = \text{Lock}   0 = \text{Release}}{0 = \text{Lock}   1 = \text{Release}}$
After reset, output is	not blocked • blocked

The possible settings on the device display are explained in the chapter *Device control* on the touch display > Drive (shading, window), page 25.

#### 7.5.6. Scenes

For the scene control, a group address for scenes must be filed in the KNX system. The output object 'Scene X' of **Cala Touch KNX** is linked to this group address. When calling or saving the scene, the scene number and, if applicable, the information 'saving' are sent via the object. With the help of the group address, it is forwarded to the scene inputs of the devices linked with the address.

In this subitem of the application the four scenes of the scene operating page are defined.

Insert the name to be shown on the menu page.

Name	[free text]
------	-------------

There are four fields for scenes on the scene page. Now define these scene memories.

Activate the scene memory and set name and scene number.

Use scene memory 1/2/3/4	<u>No</u> • Yes
Name	[free text]
Scene no.	<u>0</u> 63

Specify whether the scene can only be recalled or also saved. The storage is done by holding the button for a longer time. If this feature is enabled, set how long the key must be pressed to recognize a save command.

Scene function	<u>Activate</u> Activate and save
Hold push button down longer than (in 0.1s)> Scene save (if "and save" has been selected)	150; <u>10</u>

The status of the scene can be shown in the display menu. The status object of the scene is then evaluated as follows:

Value 0: Scene not active, name white

Value 1: Executing/settting scene, name white, flashes

Value 2: Scene executed (running, is active), name blue

Use status	<u>No</u> • Yes
------------	-----------------

The possible settings on the device display are explained in the chapter *Device control* on the touch display > Scenes, page 26.

#### 7.5.7. Universal display

In this subitem of the application, the four display areas of the universal display are defined.

Insert the name to be shown on the menu page.

There are four display areas on the Universal display page. Now define the individual fields.

Select a function. 1/0 (on / off) as well as different 8 bit, 16 bit or 32 bit values can be displayed.

Function 1/2/3/4	• <u>do not use</u>
	• 1/0
	• 8 bit value 0255
	• 8 bit value 0100%
	• 8 bit value 0360°
	<ul> <li>16 bit value counter with math. symbol</li> </ul>
	• 16 bit value counter without math. symbol
	<ul> <li>16 bit value floating point</li> </ul>
	• 32 bit value counter with math. symbol
	• 32 bit value counter without math. symbol
	<ul> <li>32 bit value floating point</li> </ul>

Enter the desired name and unit.

Name	[free text, 8 characters]
Unit	[free text, 3 characters]

The possible settings on the device display are explained in the chapter *Device control* on the touch display > Universal display, page 27.

#### 7.5.8. RGB control

This sub-item of the application determines what the menu is called and what is sent when switching off.

Insert the name to be shown on the menu page.

Name

[free text]

Select whether the 3-byte object (RGB in one object) and the three 1-byte objects (separate objects for red, green and blue) should have the value 0 when switched off or nothing.

The 3-byte object should send a 0 value if switched off	<u>No</u> • Yes
The three 1-byte objects should send a 0 value if switched off	<u>No</u> • Yes

The possible settings on the device display are explained in the chapter *Device control* on the touch display > RGB control, page 28.

#### 7.5.9. Color temperature

In this sub-item of the application, it is determined how the menu is called and the configuration options are defined.

Insert the name to be shown on the menu page.

Name	[free text]

Set the minimum and maximum settable value. Observe the specifications of the luminaire to be controlled.

Minimum variable value in K	<u>0</u> 65535
Maximum variable value in K	0 <u>65535</u>

Set the time that distinguishes the dimming command (holding down the key) from a switching command (tapping). Then select whether the dimming command will be repeated if you touch it for a longer time, by what percentage the dimming will be performed and at what frequency the command will be repeated.

Time between switching and dimming in 0.1 sec	2 50; <u>5</u>
Repetition of the dimming command	<u>No</u> • Yes
Dimming by [if the dimming command is repeated]	100,00% • 50,00% • 25,00% • <u>12,50%</u> • 6,25% • 3,13% • 1,56%
Repetition of the dimming command for long key pressure in 0.1s [if the dimming command is repeated]	2 50; <u>5</u>

The possible settings on the device display are explained in the chapter *Device control* on the touch display > Color temperature, page 29.

#### 7.5.10. HCL control

In this sub-item of the application, it is determined how the menu is called and the configuration options are defined. In addition, sequences can be configured.

Insert the name to be shown on the menu page.

Name [free text]

#### **General HCL settings**

The HCL control is interrupted when a change to manual (with switching, brightness or color temperature) is carried out via the objects 86-88. These objects can be linked with switching commands from on-site buttons for example. Also the HCL control menu of the display can be used to switch to manual.

Set the automatic reset, which ensures that the HCL control is restarted. The reset can be triggered via an object or after the expiration of the time set here.

Reset of automatic takes place	<ul> <li>according to time</li> <li>on receipt of object</li> <li>on receipt of object or according to time</li> </ul>
Reset at value (on reset on receipt of object)	0 • <u>1</u>
Time in seconds (on reset according time)	1 36000; <u>3600</u>

Set the behavior of the start / stop object, which indicates whether the HCL control is active or not. And set the behavior of the object, which indicates whether the automatic is running or has been interrupted by manual intervention.

Start/Stop object is at value	• <u>1 = start   0 = stop</u> • 0 = start   1 = stop
Start/Stop object value after reset	0 • <u>1</u>
Automatic/Manual status object is at value	• <u>1 = automatic   0 = manual</u> • 0 = manual   1 = automatic
Automatic/Manual object value after reset	0 • <u>1</u>

Set whether or in which cases times, brightnesses and color temperatures changed on the display should be saved. And determine from which change on brightness and color temperature are sent and thus the change should take effect.

Changed times, brightnesses and color temperatures shall be saved	<ul> <li><u>not</u></li> <li>after power supply restoration</li> <li>after power supply restoration and pro- gramming</li> </ul>
Send brightness values in case of change from	150%; <u>5</u>
Send color temperature values in case of change from	1500 К; <u>50</u>

#### Sequence 1/2/3/4/5/6/7/8

Set as many sequences as you need. With the same start and stop times (eg 0:00 o'clock - 0:00 o'clock) the sequence is skipped. The sequence 1 starts with the stop values of the sequence 8, therefore the values of the sequence 8 should always be set. Sequences 2-8 always begin with the stop value of the previous sequence.

First, set whether or not the sequence should be enabled for use after a reset. Unreleased sequences are skipped. Each sequence can be enabled or disabled for use directly on the **Cala Touch KNX** display.

Release after reset	No • Yes

Set a start time, and a time, brightness and color temperature for the end of the sequence.

Start time	
Hour	023
Minute	059
Second	059
Stop time	
Hour	023
Minute	059
Second	059
Brightness at stop time in %	0100; <u>50</u>
Color temperature at stop time in Kelvin	15006500; 2700

The possible settings on the device display are explained in the chapter *Device control on the touch display* > HCL control, page 30. Here, all sequences can be edited and released or blocked for use.

#### 7.5.11. Timer

This sub-item of the application is used to determine the name of the menu, as well as the activation and configuration of the timer intervals.

Insert the name to be shown on the menu page.

Na	h	าค	
INC		1e	

```
[free text]
```

First, determine if the changes introduced on the display should be kept after the power supply to the bus is restored and the device is programmed.

must be received • after	<u>n</u>
• after	restoration of power
ming	restoration of power and program-

#### Switching time 1/2/3/4/5/6/7/8

Activate as many switching times (time intervals) as you need. Switching times are shown on the display and are thus available for adjustment there only if they are accepted for use.

Use the switching time	<u>No</u> • Yes
------------------------	-----------------

Determine which weekdays the timer should be active on, and set the switch-on and switch-off time.

Active on the following days	
Monday/Tuesday//Sunday	<u>No</u> • Yes
Switch-on time:	
Hour	<u>0</u> 23
Minute	<u>0</u> 59
Second	<u>0</u> 59
Switch-off time:	
Hour	<u>0</u> 23
Minute	<u>0</u> 59
Second	<u>0</u> 59

Specify the transmission behaviour of the timer.

Transmission behaviour	<ul> <li>switch on/off   down/up</li> </ul>
	<ul> <li>only switch on   down</li> </ul>
	<ul> <li>only switch off   up</li> </ul>

Activate and configure the switching time block as necessary. Other functions in the KNX system can block the timer switch, for example, manual operation or a safety function.

Use block	<u>No</u> • Yes
Blocking object analysis	$\frac{1 = Block   0 = Release}{0 = Block   1 = Release}$
Output after reset is	not blocked • blocked

The possible settings on the device display are explained in the chapter *Device control* on the touch display > Weekly timer, page 33.

#### 7.5.12. Information pages 1 and 2

Every information page has two input objects that can be used to receive texts. These texts are displayed one under another. The texts must not exceed 14 characters in length.

Insert the name to be shown on the menu page.

Name

[free text]

### 7.6. Variable comparator

The integrated variable comparators can output maximum, minimum and average values.

Use comparator 1/2/3/4 <u>No</u> • Yes

#### 7.6.1. Control variable comparator 1/2/3/4

Determine what the control variable comparator should output, and activate the input objects to be used. Transmission patterns and blocks can also be set.

Output delivers	• Maximum value • Minimum value • <u>Average value</u>
Use input 1 / 2 / 3 / 4 / 5	No • Yes
Output sends	<ul> <li>on change of output</li> <li>on change of output and periodically</li> <li>when receiving an input object</li> <li>when receiving an input object and periodically</li> </ul>
Send cycle ( <i>if sent periodically</i> )	5 s • 10 s • 30 s • • <u>5 min</u> • • 2 h
At and above change of ( <i>if sent on change</i> )	1% • 2% • 5% • <u>10%</u> • 20% • 25% • 50%
Analysis of the blocking object	• at value 1: block   at value 0: release • at value 0: block   at value 1: release
Blocking object value before 1st communication	0•1
Behaviour of the switching output	
On block	<ul> <li><u>do not send message</u></li> <li>Send value</li> </ul>
Sent value in %	0 100
output sends on release (with 2 seconds release delay)	• the current value • the current value after receipt of an object

# 7.7. Computer

Activate the multi-functional computer, with which the input data can be changed by calculation, querying a condition or converting the data point type. The menus for the further setting of the computer are then displayed.

Computer 1/2/3/4/5/6/7/8

No • Yes

#### 7.7.1. Computers 1-8

Set, in which cases input values received are to be kept per object. Please note that the setting "After power restoration and programming" should not be used for the initial
start-up, as the factory settings are always used until the first call (setting via objects is ignored).

Maintain the	
input values received via communication objects	<ul> <li>never</li> <li>after power supply restoration</li> <li>after power supply restoration and programming</li> </ul>

Select the function set the input mode and starting values for input 1 and input 2.

Function (I = Input)	• Prerequisite: $E1 = E2$ • Prerequisite: $E1 > E2$ • Prerequisite: $E1 > E2$ • Prerequisite: $E1 < E2$ • Prerequisite: $E1 < E2$ • Prerequisite: $E1 - E2 > E3$ • Prerequisite: $E1 - E2 > E3$ • Prerequisite: $E1 - E2$ amount $> E3$ • Calculation: $E1 + E2$ • Calculation: $E1 - E2$ Amount • Calculation: Output $1 = E1 \times X + Y  $ • Output $2 = E2 \times X + Y  $ • Transformation: General
Tolerance for comparison ( <i>in the case of prerequisite E1 = E2</i> ) Input type	<ul> <li><u>0</u> 4,294,967,295</li> <li>[Selection options depending on the function]</li> <li>1 bit</li> <li>1 byte (0255)</li> <li>1 byte (0%100%)</li> <li>1 byte (0%360°)</li> <li>2 byte counter without math. symbol</li> <li>2 byte counter with math. symbol</li> <li>2 byte floating point</li> <li>4 byte counter without math. symbol</li> <li>4 byte counter with math. symbol</li> <li>4 byte counter with math. symbol</li> <li>4 byte counter with math. symbol</li> <li>4 byte floating point</li> </ul>
Starting value E1 / E2 / E3	[Input range depending on the type of input]

## Prerequisites

When querying the prerequisites set the output type and output values at different statuses:

Output type	<ul> <li>1 bit</li> <li>1 byte (0255)</li> <li>1 byte (0%100%)</li> <li>1 byte (0°360°)</li> <li>2 byte counter without math. symbol</li> <li>2 byte counter with math. symbol</li> <li>2 byte floating point</li> <li>4 byte counter without math. symbol</li> <li>4 byte counter with math. symbol</li> <li>4 byte floating point</li> <li>4 byte floating point</li> </ul>
Output value (if applicable output value A1 / A2)	
if the condition is met	$\underline{0}$ [Input range depending on the type of output]
if the condition is not met	$\underline{0}$ [Input range depending on the type of output]
if the monitoring time period is exceeded	$\underline{0}$ [Input range depending on the type of output]
if blocked	$\underline{0}$ [Input range depending on the type of output]

#### Set the output send pattern.

Output sends	<ul> <li>on change on change and after reset</li> <li>on change and periodically</li> <li>when receiving an input object</li> <li>when receiving an input object and periodically</li> </ul>
Type of change (is only sent if "on change" is selected)	<ul> <li>on each change</li> <li>on change to condition met</li> <li>on change to condition not met</li> </ul>
Send cycle (if sent periodically)	5 s 2 h; <u>10 s</u>

Set the text to be displayed for conditions met / not met.

Text if the condition is met	[Free text max. 14 chars.]
Text if the condition is not met	[Free text max. 14 chars.]

If applicable set the send delays.

Send delay in the event of change to the condition is met	<u>none</u> • 1 s • • 2 h
Send delay in the event of change to the condition is not met	<u>none</u> • 1 s • • 2 h

## **Calculations and transformation**

For calculations and transformations set the output values to the various conditions:

Output value (if applicable A1 / A2)	
if the monitoring time period is exceeded	<u>0</u> [Input range depending on the type of output]
if blocked	<u>0</u> [Input range depending on the type of output]

Set the output send pattern.

Output sends	<ul> <li>on change</li> <li>on change and after reset</li> <li>on change and periodically</li> <li>when receiving an input object</li> <li>when receiving an input object and periodically</li> </ul>
on change of (only if calculations are transmitted for changes)	1 [Input range depending on the type of input]
Send cycle (if sent periodically)	5 s 2 h; <u>10 s</u>

For **Calculations of the form output 1 = E1 \times X + Y | output 2 = E2 \times X + Y define the variables X and Y. The variables can have a positive or negative sign, 9 digits before and 9 digits after the decimal point.** 

Formula for output A1: A1 = E1 × X + Y		
Х	1.00 [free input]	
Y	0.00 [free input]	
Formula for output A2: A2 = E2 $\times$ X + Y		
Х	1.00 [free input]	
Y	0.00 [free input]	

#### Further settings for all formulas

If necessary, activate the input monitoring. Set which inputs are to be monitored, at which intervals the inputs are to be monitored and what value the "monitoring status" should have, if the monitoring period is exceeded without feedback.

Use input monitoring	<u>No</u> •Yes
Monitoring of	• <u>E1</u>
	• E2
	• E3
	• E1 and E2
	• E1 and E3
	• E2 and E3
	• E1 and E2 and E3
	[depending on the function]

Monitoring period	5 s • • 2 h; <u>1 min</u>
Value of the object "monitoring status"	0 • <u>1</u>

If necessary, activate the computer block and set what a 1 or 0 at the block entry means and what happens in the event of a block.

Use block	<u>No</u> •Yes
Analysis of the blocking object	At value 1: block   At value 0: release     At value 0: block   At value 1: release
Value before first call	<u>0</u> •1
Output pattern On block	<ul> <li>do not send anything</li> <li>send value</li> </ul>
On release	<ul> <li>as send pattern [see above]</li> <li>send current value immediately</li> </ul>

# 7.8. Logic

The device has 16 logic inputs, eight AND and eight OR logic gates.

Activate the logic inputs and assign object values up to first call.

Use logic inputs	Yes • <u>No</u>
Object value prior to first call for:	
- Logic input 1	<u>0</u> • 1
- Logic input	<u>0</u> •1
- Logic input 16	<u>0</u> •1

Activate the required logic outputs.

# **AND** logic

AND logic 1	not active • active
AND logic	not active • active
AND logic 8	not active • active

# **OR** logic

OR logic 1	not active • active
OR logic	not active • active
OR logic 8	not active • active

# 7.8.1. AND logic 1-8 and OR logic outputs 1-8

The same setting options are available for AND and OR logic.

Each logic output may transmit one 1 bit or two 8 bit objects. Determine what the out put should send if logic = 1 and = 0.

1. / 2. / 3. / 4. Input	<u>do not use</u> Logic inputs 116     Logic inputs 116 inverted     all switching events that the device     provides (see <i>Connection inputs of the AND/OR logic</i> )
Output type	• a 1-Bit-object • two 8-bit objects

If the output type is a 1-bit object, set the output values for the various conditions.

Output value if logic = 1	<u>1</u> •0
Output value if logic = 0	1 • <u>0</u>
Output value If block is active	1 • <u>0</u>
Output value if monitoring period is exceeded	1 • <u>0</u>

If the **output type is two 8-bit objects**, set the type of object and the output values for the various conditions.

Object type	• Value (0255) • Percent (0100%) • Angle (0360°) • Scene call-up (0127)
Output value object A if logic = 1	0 255 / 100% / 360° / 127; <u>1</u>
Output value object B if logic = 1	0 255 / 100% / 360° / 127; <u>1</u>
Output value object A if logic = 0	0 255 / 100% / 360° / 127; <u>0</u>
Output value object B if logic = 0	0 255 / 100% / 360° / 127; <u>0</u>
Output value object A if block is active	0 255 / 100% / 360° / 127; <u>0</u>
Output value object B if block is active	0 255 / 100% / 360° / 127; <u>0</u>
Output value object A if monitoring period is exceeded	0 255 / 100% / 360° / 127; <u>0</u>
Output value object B if monitoring period is exceeded	0 255 / 100% / 360° / 127; <u>0</u>

Send pattern	<ul> <li>on change of logic</li> <li>on change of logic to 1</li> <li>on change of logic to 0</li> <li>on change of logic and periodically</li> <li>on change of logic to 1 and periodically</li> <li>on change of logic to 0 and periodically</li> <li>on change of logic+object receipt</li> <li>on change of logic+object receipt</li> <li>and periodically</li> </ul>
Send cycle (if sent periodically)	5 s • <u>10 s</u> • • 2 h

Set the output send pattern.

# Block

If necessary, activate the block for the logic output and set what a 1 or 0 at the block input means and what happens in the event of a block.

Use block	<u>No</u> •Yes
Analysis of the blocking object	<u>At value 1: block   At value 0: release</u> At value 0: block   At value 1: release
Blocking object value before first call	<u>0</u> •1
Output pattern On block	<ul> <li><u>Do not send message</u></li> <li>Transmit block value [see above, Output value if blocking active]</li> </ul>
On release (with 2 seconds release delay)	[send value for current logic status]

# Monitoring

If necessary, activate the input monitoring. Set which inputs are to be monitored, at which intervals the inputs are to be monitored and what value the "monitoring status" should have, if the monitoring period is exceeded without a feedback being given.

Use input monitoring	<u>No</u> • Yes
Input monitoring	• 1 • 2 • 3 • 4 • 1 + 2 • 1 + 3 • 1 + 4 • 2 + 3 • 2 + 4 • 3 + 4
	• $1 + 2 + 3 \cdot 1 + 2 + 4 \cdot 1 + 3 + 4 \cdot 2 + 3 + 4$ • $1 + 2 + 3 + 4$
Monitoring period	5 s • • 2 h; <u>1 min</u>
Output behaviour on exceeding the moni- toring time	<ul> <li><u>Do not send message</u></li> <li>Send value exceeding [= value of the parameter "monitoring period"]</li> </ul>

# 7.8.2. Connection inputs of the AND logic

do not use

Logic input 1 Logic input 1 inverted Logic input 2 Logic input 2 inverted Logic input 3 Logic input 3 inverted Logic input 4 Logic input 4 inverted Logic input 5 Logic input 5 inverted Logic input 6 Logic input 6 inverted Logic input 7 Logic input 7 inverted Logic input 8 Logic input 8 inverted Logic input 9 Logic input 9 inverted Logic input 10 Logic input 10 inverted Logic input 11 Logic input 11 inverted Logic input 12 Logic input 12 inverted Logic input 13 Logic input 13 inverted Logic input 14 Logic input 14 inverted Logic input 15 Logic input 15 inverted Logic input 16 Logic input 16 inverted

#### For devices with temperature sensor:

Temperature sensor malfunction ON Temperature sensor malfunction OFF Switching output 1 Temperature Switching output 1 Temperature inverted Switching output 2 Temperature Switching output 2 Temperature Switching output 3 Temperature Switching output 3 Temperature Switching output 4 Temperature Switching output 5 Temperature Switching output 6 Temperature Switching output 7 Temperature Switching output 8 Temperature Switching output 9 Temperature Switching output 9 Temperature Switching output 9 Temperature Switching output 9 Temperature Switching 0 Eco temperature controller active Eco temperature controller inactive Frost protection temperature controller active Frost protection temperature controller inactive Heating 1 temperature controller active Heating 2 temperature controller active Heating 2 temperature controller active Cooling 1 temperature controller active Cooling 1 temperature controller active Cooling 1 temperature controller active Cooling 2 temperature controller active

#### For devices with humidity sensor:

Humidity sensor malfunction ON Humidity sensor malfunction OFF Switching output 1 Humidity Switching output 1 Humidity inverted Switching output 2 Humidity Switching output 2 Humidity inverted Switching output 3 Humidity Switching output 3 Humidity inverted Switching output 4 Humidity Switching output 4 Humidity inverted Switching output coolant temperature Switching output coolant temperature inv. Room temperature is comfortable Room temperature is uncomfortable Humidity controller de-humidification 1 active Humidity controller de-humidification 1 inactive Humidity controller de-humidification 2 active Humidity controller de-humidification 2 inactive Humidity controller humidification active Humidity controller humidification 1 inactive

## For devices with CO<sub>2</sub> sensor:

CO2 sensor malfunction ON CO2 sensor malfunction OFF Switching output 1 CO2 Switching output 1 CO2 inverted Switching output 2 CO2 Switching output 2 CO2 inverted Switching output 3 CO2 Switching output 3 CO2 inverted Switching output 4 CO2 Switching output 4 CO2 Switching output 4 CO2 inverted CO2 controller ventilation 1 active CO2 controller ventilation 1 inactive CO2 controller ventilation 2 active CO2 controller ventilation 2 inactive

# 7.8.3. Connection inputs of the OR logic

The OR logic connection inputs correspond to those of the AND logic. In addition the following inputs are available for the OR logic:

Switching output AND logic 1 Switching output AND logic 1 inverted Switching output AND logic 2 Switching output AND logic 2 inverted Switching output AND logic 3 Switching output AND logic 3 inverted Switching output AND logic 4 Switching output AND logic 4 inverted Switching output AND logic 5 Switching output AND logic 5 inverted Switching output AND logic 6 Switching output AND logic 6 inverted Switching output AND logic 7 Switching output AND logic 7 inverted Switching output AND logic 8 Switching output AND logic 8 inverted

# 7.9. Button interfaces

Mechanical buttons or temperature sensors T-NRC (Elsner Elektronik item number 30516) can be attached to the four analogue/digital inputs of the **Cala Touch KNX**.

Activate the interfaces you want to use.

Use interface 1/2/3/4	No • Yes

# 7.9.1. Interface 1-4

Choose a function:

Bus function	• Switch
	<ul> <li>Changeover switch</li> </ul>
	Shutter
	• Blinds
	Awning
	Window
	• Dimmer
	• 8-bit encoder
	• 16-bit encoder
	<ul> <li>Scene activation / scene saving</li> </ul>
	<ul> <li>Temperature sensor NTC</li> </ul>

#### Input as switch:

If a button with switch function is assigned to the input, select the bus function "Switch" and specify which value is sent when pressing/releasing the button and when it will be sent.

Bus function	Switch
Command when pressing the button	• send 0
	• send 1
	<ul> <li>do not send telegram</li> </ul>
Command when releasing the button	• send 0
	• send 1
	<ul> <li>do not send telegram</li> </ul>
Send value	• <u>on change</u>
	<ul> <li>for change to 1</li> </ul>
	<ul> <li>for change to 0</li> </ul>
	<ul> <li>for change and cyclical</li> </ul>
	<ul> <li>for change to 1 and cyclical</li> </ul>
	<ul> <li>for change to 0 and cyclical</li> </ul>
Send all values	5 s 2 h
(only if sent as "cyclical")	

#### Input as selector switch:

If a button with switch function is assigned to the input, select the bus function "Selector switch" and specify if the button should switch when pressed/released..

Bus function	Selector switch
Command when pressing the button	<ul><li>selector switch</li><li>do not send telegram</li></ul>
Command when releasing the button	<ul><li>selector switch</li><li>do not send telegram</li></ul>

#### Input to shutter, blinds, awning or window control:

If the input to the drive control is used via the bus, select the bus function "shutter", "awning", "blinds" or "window" and specify the button function and control mode.

Function	Shutter / blinds / aw	ning / window
Button function	$ \begin{array}{c} \underbrace{Up}_{p} \bullet Down\\ \underbrace{Up}_{p} \bullet Down \bullet Up \\ Down\\ \underbrace{On}_{p} \bullet Off \bullet On \\ \hline Open \\ \bullet Closed \bullet \\ \hline Open \\ \hline Closed \\ \end{array} $	(shutter) (blinds) (awning) (window)
Control mode*	• <u>Standard</u> • Standard inverted • Comfort mode • Dead man's switch	

\* For further details about settings, please see  $\square$  "Control modes for drive control" auf Seite 82

#### Input as dimmer:

If the input is used as a dimmer, select the bus function "Dimmer" and specify the button function, time interval (switching/dimming) and if requested, the repeat interval for a long button press.

Function	Dimmer
Button function	brighter • darker • brighter/darker
Time between switching and dimming (in 0.1 s)	150; <u>5</u>
Repeat the dimm command	<u>no</u> •yes
Repeat the dimm command for a long button press ( <i>if dimm command is repeated</i> )	every 0.1 s • every 2 sec; every 0,5 sec
Dim by (if dimm command is repeated)	1,50% • 3% • <u>6 %</u> • 12,50% • 25% • 50%

#### Input 8 bit encoder:

If the input is to be used as an 8bit encoder, select the "8 bit encoder" bus function and specify which value will be sent.

Bus function	8 bit encoder
Value	-67076006707600; <u>0</u>

#### Input 16 bit encoder:

If the input is to be used as a 16bit encoder, select the "16 bit encoder" bus function and specify which value will be sent.

Function	16 bit encoder
Value in 0.1	-67076006707600; <u>0</u>

#### Input for scenario control:

If the input is to be used for recalling and saving a scene, select the bus function "scene call-up" and decide whether the button should be used to save the scene as well (keep pressed for longer).

Bus function	Scenario recall
Scenario no.	<u>0</u> 63
Scenario function	Activate     Activate and save
Press key for longer than (in 0.1 s) Scenario saving only for saving	1 <u>50</u>

#### Temperature sensor

If a temperature sensor T-NTC is connected to the input, set the behaviour (malfunction object, transmission behaviour) and mixed-value calculation here. If the measured values of the sensor should deviate from the actual temperature values (e.g. in case the installation site is not in an ideal position), this may be offset and corrected.

Bus function	Temperature sensor NTC	
Use malfunction object	Yes ● <u>No</u>	
Offset in 0.1°C	-5050; <u>0</u>	
Use external measured value	Yes • <u>No</u>	
Ext. Measured value portion of the total reading only if an external value is used	5% • • <u>50%</u> • • 100%	
All of the following settings then pertain to the total measured value		
Send behaviour	<ul> <li>periodically</li> <li>on change</li> <li>on change and periodically</li> </ul>	
On change of <i>if transmitted on change</i>	0.1°C • • <u>0.5°C</u> • • 5.0°C	
Send cycle if transmitted periodically	<u>5 s</u> 2 h	

# 7.9.2. Control modes for drive control

#### Behaviour on button actuation in standard control mode:

	short:	press and hold:
Blind	Stop/step	Up or Down
Roller Shutter	Stop	Up or Down
Awning	Stop	Retract or Extend
Window	Stop	Close or Open

## Standard:

If briefly operated, the drive will move incrementally or stops. If operated longer, the drive will move up to the end position. The time difference between "short" and "long" is set individually.

Control mode	Standard
Behavior during button operation: short = stop/increment long = Up or Down	
Time between short and long in 0.1 seconds	150; <u>10</u>

## Standard inverted:

When pushed shortly, the drive moves up to the end position. When pushed for longer, the drive moves incrementally or stops. The time difference between "short" and "long" and the repeat interval is set individually.

Control mode	Standard inverted
Behavior during button operation: short = Up or Down long = Stop/Step	
Time between short and long in 0.1 seconds	150; <u>10</u>
Repeat the step command for a long button press	every 0.1 s • every 2 sec; every 0.5 sec

#### Comfort mode:

In the **comfort mode** actuating the button briefly, a bit longer and long will trigger different responses of the drive. The time intervals are set individually.

**Short actuation** (shorter than Time 1): The drive is positioned step-wise and stopped. **Holding it slightly longer** (longer than Time 1, but shorter than Time 1+2): Drive running. Drive stops when the button is released.

**Long holding** (release after Time 1+2 runs out): Drive moves independently to the end position. The movement can be interrupted by a short tap.

Fig. 35 Time interval comfort mode diagram

Time 1	Time 2	
0 1	1	1 + 2
Point in time 0:		Actuate of button, start of time 1
Release before ti	me 1 expired:	step (or stop if drive is moving)
Point in time 1:		End of time 1, start of time 2 Moving command
Release after time	e 1 expired	
but before time 2	expires:	Stop
Release after time	e 1 + 2 expired:	Move into end position
Control mode		Comfort mode
Behavior during b Button is pushed released before ti held longer than released between released after tim	button operation: and me 1 expired = stop/step time 1 = Up or Down time 1 and 1-2= stop te 1 +2 = no more stop	
Time 1		0.0s • 2 s; <u>0.4 s</u>
Time 2		0 s • 2 s; 2 s

## Dead man's switch:

The drive moves as soon as the button is actuated and stops as soon as the button is released.

Control mode	Dead man's switch
Behavior during button operation: Push button = Up or Down command Release button = Stop command	

# 8. Temperature parameter settings

In the following all parameters are described that are found in devices with a temperature sensor, i.e. in Cala KNX T, Cala KNX TH and Cala KNX AQS/TH.

# 8.1. Temperature Measurement

Select, whether a **malfunction object** is to be sent if the sensor is faulty.

Use malfunction object	No • Yes
-	

Use Offsets to adjust the readings to be sent.

Offset in 0.1°C	-5050; <u>0</u>

The unit can calculate a **mixed value** from its own reading and an external value. Set the mixed value calculation if desired. If an external portion is used, all of the following settings (threshold values, etc.) are related to the overall reading.

Use external measured value	<u>No</u> •Yes
Ext. Reading proportion of the total reading	5% • 10% • • <u>50%</u> • • 100%
Sending pattern for internal and total measured value	<ul> <li><u>never</u></li> <li>periodically</li> <li>on change</li> <li>on change and periodically</li> </ul>
At and above change of ( <i>if sent on change</i> )	0.1°C • 0.2°C • <u>0.5°C</u> • • 5.0°C
Send cycle (if sent periodically)	5 s • <u>10 s</u> • • 2 h

The **minimum and maximum readings** can be saved and sent to the bus. Use the "Reset temperature min/max. value" objects to reset the values to the current readings. The values are not retained after a reset.

Use minimum and maximum value	<u>No</u> • Yes
-------------------------------	-----------------

# 8.2. Temperature threshold values

Activate the required temperature threshold values. The menus for setting the threshold values are displayed.

Use threshold value 1/2/3/4 Yes • No

# 8.2.1. Threshold value 1, 2, 3, 4

# Threshold value

Set, in which cases **threshold values and delay times** received via object are to be retained. The parameter is only taken into consideration if the setting via object is ac-

tivated below. Please note that the setting "After power supply restoration and programming" should not be used for the initial start-up, as the factory settings are always used until the first communication (setting via objects is ignored).

Maintain the	
threshold values and delays received via communication objects	<ul> <li><u>never</u></li> <li>after power supply restoration</li> <li>after power supply restoration and programming</li> </ul>

Set the threshold value directly in the application program using parameters, or define them via the bus using a communication object.

#### Threshold value setting via parameter:

Set the threshold values and hysteresis directly.

Threshold value setting via	Parameter • Communication objects
Threshold value in 0.1°C	-300 800; <u>200</u>

#### Threshold value setting via a communication object:

Define, how the threshold value is to be received from the bus. Basically, a new value can be received, or simply a command to increase or decrease.

During initial commissioning, a threshold value must be defined, which will be valid until the first communication with a new threshold value. For units which have already been taken into service, the last communicated threshold value can be used. Basically, a temperature range is given, in which the threshold value can be changed (object value limit).

A set threshold value will be retained until a new value or a change is transferred. The current value is saved, so that it is retained in the event of a power supply failure and will be available once the power supply is restored.

Threshold value setting via	Parameter • Communication objects
Start threshold value in 0.1°C valid until first communication	-300 800; <u>200</u>
Object value limit (min) in 0.1°C	<u>-300</u> 800
Object value limit (max) in 0.1°C	-300 <u>800</u>
Type of threshold value change	Absolute value
Increment (upon increase/decrease change)	<u>0.1°C</u> • • 5°C

Set the hysteresis independent of the type of threshold value specification.

Hysteresis setting	in % • <u>absolute</u>
Hysteresis in 0.1°	01100; <u>50</u>
Hysteresis in % of the threshold value	0 50; <u>20</u>

# Switching output

Set the behaviour of the switching output when a threshold value is exceeded/undercut. The output switching delay can be set using objects or directly as a parameter.

When the following conditions apply, the output is (TV = Threshold value)	<ul> <li>TV above = 1   TV - hyst. below = 0</li> <li>TV above = 0   TV - hyst. below = 1</li> <li>TV below = 1  TV + hyst. above = 0</li> <li>TV below = 0  TV + hyst. above = 1</li> </ul>
Delays can be set via objects (in seconds)	<u>No</u> • Yes
Switching delay from 0 to 1 (If delay can be set via objects: valid until 1st communication)	<u>None</u> • 1 s • 2 s • 5 s • 10 s • • 2 h
Switching delay from 1 to 0 (If delay can be set via objects: valid until 1st communication)	<u>None</u> • 1 s • 2 s • 5 s • 10 s • • 2 h
Switching output sends	<ul> <li>on change on change to 1</li> <li>on change to 0</li> <li>on change and periodically</li> <li>on change to 1 and periodically</li> <li>on change to 0 and periodically</li> </ul>
Cycle (only if sending periodically is selected)	<u>5 s</u> • 10 s • 30 s • 2 h

# Block

The switching output can be blocked using an object.

Use switching output block	<u>No</u> •Yes
----------------------------	----------------

If the block is activated, define specifications here for the behaviour of the output when blocked.

Analysis of the blocking object	At value 1: block   At value 0: release     At value 0: block   At value 1: release	
Blocking object value before 1st communication	<u>0</u> • 1	
Behaviour of the switching output		
On block	• Do not send message • send 0 • send 1	
On release (with 2 seconds release delay)	[Dependent on the "Switching output sends" setting]	

The behaviour of the switching output on release is dependent on the value of the parameter "Switching output sends" (see "Switching output")

Switching output sends on change	<ul> <li>Do not send message</li> </ul>
	<ul> <li>Send switching output status</li> </ul>

Switching output sends on change to 1	<ul> <li>Do not send message</li> <li>if switching output = 1 → send 1</li> </ul>
Switching output sends on change to 0	<ul> <li>Do not send message</li> <li>if switching output = 0 → send 0</li> </ul>
Switching output sends on change and periodically	Send switching output status
Switching output sends on change to 1 and periodically	if switching output = $1 \rightarrow$ send 1
Switching output sends on change to 0 and periodically	if switching output = $0 \rightarrow \text{send } 0$

# 8.3. Temperature PI control – Independent controller

Activate the control.

Use control	No • Yes

Determine if this device should take over the temperature control (stand-alone controller), or if the Cala display should act as an extension for operating another controller.

Intended as a	Stand-alone controller
	<ul> <li>Controller extension (for operating a</li> </ul>
	stand-alone controller only)

The settings for the 'Stand-alone controller' option are described below. For configuration as an extension, please see Chapter *Temperature PI control – Controller extension unit*, page 98.

# **General control**

Set, in which cases **setpoint values and extension time** received via object are to be retained. The parameter is only taken into consideration if the setting via object is activated below. Please note that the setting "After power supply restoration and programming" should not be used for the initial start-up, as the factory settings are always used until the 1st communication (setting via objects is ignored).

Maintain the	
Target values and extension time received via communication objects	<ul> <li>never</li> <li>after power supply restoration</li> <li>after power supply restoration and programming</li> </ul>

For an adequate regulation of the ambient temperature, comfort, standby, eco and building protection modes may be used.

Comfort when present,

Standby during short absences,

Eco as a night-time mode and

Frost/heat protection (building protection) e. g. with the window open.

The settings for the temperature control include the setpoint temperatures for the individual modes. Objects are used to determine which mode is to be selected. A change of mode may be triggered manually or automatically (e.g. by a timer, window contact).

The **mode** may be switched with two 8 bit objects of different priority. Objects

"... HVAC mode (Prio 2)" for switching in everyday operation and

"... HVAC mode (Prio 1)" for central switching with higher priority.

The objects are coded as follows:

0 = Auto

1 = Comfort

2 = Standby

3 = Eco

4 = Building Protection

Alternatively, you can use three objects, with one object switching between eco and standby mode and the two others activating comfort mode and frost/heat protection mode respectively. The comfort object blocks the eco/standby object, and the frost/ heat protection object has the highest priority. Objects

"... Mode (1: Eco, 0: Standby)",

"... comfort activation mode" and

"... frost/heat protection activation mode"

Switch mode via	• two 8 Bit objects (HVAC Modes)
	• three 1 bit objects

Select the **mode to be activated after reset** (e.g. power failure, reset of the line via the bus) (Default).

Then configure a temperature control **block** via the blocking object.

Mode after reset	• Comfort
	Standby
	• Eco
	<ul> <li>Building protection</li> </ul>
Behaviour of the blocking object with value	• 1 = Block   0 = release
	• 0 = block   1 = release
Value of the blocking object after reset	<u>0</u> •1

Specify when the current **control variables** of the controller are to be **sent** to the bus. Periodic sending is safer, in case a message does not reach a recipient. You may also set up periodical monitoring by the actuator with this setting.

Send control variable	<ul> <li><u>on change</u></li> <li>on change and periodically</li> </ul>
from change (in % absolute)	110; <u>2</u>
Cycle (if sent periodically)	5 s • • <u>5 min</u> • • 2 h

The **status object** reports the current status of the control variables (0% = OFF, >0% = ON) and may for example be used for visualisation, or to switch off the heating pump as soon as the heating is switched off.

Send status objects	<ul> <li>on change</li> <li>on change to 1</li> <li>on change to 0</li> <li>on change and periodically</li> <li>on change to 1 and periodically</li> <li>on change to 0 and periodically</li> </ul>
Cycle (if sent periodically)	5 s • • <u>5 min</u> • • 2 h

Then define the **type of control**. Heating and/or cooling may be controlled in two levels.

Type of control	<ul> <li>Single level heating</li> <li>Dual-level heating</li> <li>Single-level cooling</li> <li>Single-level heating + single-level cooling</li> </ul>
	<ul> <li>Dual-level heating + single-level cooling</li> </ul>
	<ul> <li>Dual-level heating + dual-level cooling</li> </ul>

## **General setpoint values**

Determine if the modified set point values should be kept after a mode change, or if they should reset to the standard specified here.

Keep modified set points after mode	No • <u>Yes</u>
change	

You may enter separate setpoint values for each mode or use the comfort setpoint as a basic value.

If you are using the control for both heating *and* cooling, you may also select the setting "separately with switching object". Systems used for cooling in summer and for heating in winter can thus be switched from one to the other.

If you are using the basic value, only the deviation from the comfort setpoint value is listed for the other modes (e.g, 2°C less for standby mode).

Setting the setpoint values	<ul> <li>with separate setpoint values with Switching object</li> <li>with separate setpoint values without Switching object</li> <li>with comfort setpoint as a basis with Switching object</li> <li>with comfort setpoint as a basis without Switching object</li> </ul>
Behaviour of the switching object at value (with switching object)	• <u>0</u> = Heating   1 = Cooling • 1 = Heating   0 = Cooling
Value of the switching object after reset (with switching object)	<u>0</u> • 1

The **increment** for the setpoint changes is predefined. Whether the change only remains temporarily active (not saved) or is also retained after power supply restoration (and programming), is specified in the first section of "General control". This also applies to a comfort extension.

Increment for setpoint changes	1 50; <u>10</u>
(in 0.1 °C)	

The control may be reset to comfort mode from eco mode, which is used as night mode, via the comfort extension. This allows the user to maintain the comfort setpoint value for a longer time, e.g. when having guests. The duration of this comfort extension period is set. After the comfort extension period expires, the system returns to eco mode.

Comfort extension time in seconds	136000; <u>3600</u>
(can only be activated from eco mode)	

# **Comfort Setpoint**

Comfort mode is usually used for daytime mode when people are present. A starting value is defined for the comfort setpoint as well as a temperature range in which the setpoint value may be modified.

Starting heating/cooling setpoint (in 0.1 °C)	-300800; <u>210</u>
(not upon saving the setpoint value after	
programming)	

## If setpoint values are entered separately:

Min. object value heating/cooling (in 0.1 °C)	-300800; <u>160</u>
Max. object value heating/cooling (in 0.1 °C)	-300800; <u>280</u>

#### If the comfort setpoint value is used as a basis:

If the comfort setpoint value is used as a basis, the reduction/increment of the value is set.

Minimum base setpoint (in 0.1°C)	-300800; <u>160</u>
Maximum base setpoint (in 0.1°C)	-300800; <u>280</u>
Reduction by up to (in 0.1°C)	0200; <u>50</u>
Increase by up to (in 0.1°C)	0200; <u>50</u>

If the comfort setpoint is used as the basis without a switching object, a dead zone is specified for the control mode "heating *and* cooling" to avoid direct switching from heating to cooling.

Dead zone between heating and cooling	1100; <u>50</u>
(only if both heating AND cooling are used)	

## Standby setpoint

Standby mode is usually used for daytime mode when people are absent.

#### If setpoint values are entered separately:

A starting setpoint value is defined as well as a temperature range in which the setpoint value may be changed.

Starting heating/cooling setpoint (in 0.1 °C) valid until 1st communication	-300800; <u>210</u>
Min. object value heating/cooling (in 0.1 °C)	-300800; <u>160</u>
Max. object value heating/cooling (in 0.1 °C)	-300800; <u>280</u>

#### If the comfort setpoint value is used as a basis:

If the comfort setpoint value is used as a basis, the reduction/increment of the value is set.

Reduce heating setpoint (in 0.1°C) (for heating)	0200; <u>30</u>
Increase cooling setpoint (in 0.1°C) (for cooling)	0200; <u>30</u>

## **Eco setpoint**

Eco mode is usually used for night mode.

#### If setpoint values are entered separately:

A starting setpoint value is defined as well as a temperature range in which the setpoint value may be changed.

Starting heating/cooling setpoint (in 0.1 °C) valid until 1st communication	-300800; <u>210</u>
Min. object value heating/cooling (in 0.1 °C)	-300800; <u>160</u>
Max. object value heating/cooling (in 0.1 °C)	-300800; <u>280</u>

#### If the comfort setpoint value is used as a basis:

If the comfort setpoint value is used as a basis, the reduction/increment of the value is set.

Reduce heating setpoint (in 0.1°C) (for heating)	0200; <u>50</u>
Increase cooling setpoint (in 0.1°C) (for cooling)	0200; <u>60</u>

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# Setpoint values for frost/heat protection (building protection)

The building protection mode is for example used as long as windows are opened for ventilation. Setpoints for frost protection (heating) and heat protection (cooling) are determined which may not be modified from outside (no access via operating devices etc.). The building protection mode may be activated with delay, which allows you to leave the building before the controls switch to frost/heat protection mode.

Setpoint frost protection (in 0.1°C)	-300800; <u>70</u>
Activation delay	less than ● 5 s ● ● <u>5 min</u> ● ● 2 h
Setpoint heat protection (in 0.1°C)	-300800; <u>350</u>
Activation delay	less than • 5 s • • <u>5 min</u> • • 2 h

# **General control variables**

This setting appears for the control types "Heating *and* Cooling" only. Here, you can decide whether to use a common control variable for heating and cooling. If the 2nd level has a common control variable, you also determine the control mode of the 2nd level here.

For heating and cooling	<ul> <li>separate control variables are used</li> <li>common control variables are used for Level 1</li> <li>common control variables are used for Level 2</li> <li>common control variable are used for Level 1+2</li> </ul>
Use control variable for 4/6-way valve (only for common control variables in level 1)	<u>No</u> •Yes
Control type (for level 2 only)	• 2-point-control • Pl control
Control variable of the 2nd Level is on (only for level 2 with 2 point controlling)	• <u>1 bit object</u> • 8 bit object

When using the control variable for a 4/6 way valve, the following applies:

0%...100% heating = 66%...100% control variable

OFF = 50% control variable

0%...100% cooling = 33%...0% control variable

# 8.3.1. Heating control level 1/2

If a heating control mode is configured, one or two setting sections for the heating levels are displayed.

In the 1st level, heating is controlled by a PI control, which allows to either enter control parameters or select predetermined applications.

In the 2nd level (therefore only in case of 2-level heating), heating is controlled via a PI or a 2-point-control.

 

 Setpoint difference between 1st and 2nd level (in 0.1°C) (for level 2)
 0...100; <u>40</u>

 Control type (for level 2, no common control variables)
 •2-point-control •Pl control

 Control variable is a (for level 2 with 2-point controlling, no
 •1 bit object •8 bit object

In level 2, the setpoint difference between the two levels must also be specified, i.e. below which setpoint deviation the second level is added.

#### PI control with control parameters:

common control variables)

This setting allows individual input of the parameters for PI control.

Control type	• PI control
Setting of the controller by	Controller parameter
	<ul> <li>specified applications</li> </ul>

Specify the deviation from the setpoint value at which the maximum control variable value is reached, i.e. the point at which maximum heating power is activated.

The reset time shows how quickly the controller responds to deviations from the setpoint value. In case of a short reset time, the control responds with a fast increase of the control variable. In case of a long reset time, the control responds somewhat less urgently and needs longer until the necessary control variable for the setpoint value deviation is reached.

You should set the time appropriate to the heating system at this point (observe manufacturer's instructions).

Maximum control variable is reached at setpoint/actual difference of (in °C)	0 <u>5</u>
Reset time (in min.)	1255; <u>30</u>

Now specify what should be sent when the control is blocked. Set a value greater 0 (=OFF) to receive a basic heating level, e.g. for floor heating.

On release, the control variable follows the rule again.

When blocked, the control variable shall	<u>not be sent</u> send a specific value
Value (in %) ( <i>if a value is sent</i> )	<u>0</u> 100

In case of a common control variable for heating and cooling, 0 is always transmitted as a fixed value.

#### PI control with predetermined application:

This setting provides fixed parameters for frequent applications.

Control type	• PI control
Setting of the controller by	<ul> <li>Controller parameter</li> <li>specified applications</li> </ul>

Application	<ul> <li>Warm water heating</li> <li>Floor heating</li> <li>Convection unit</li> <li>Electric heating</li> </ul>
Maximum control variable is reached at setpoint/actual difference of (in °C)	Warm water heating: 5 Floor heating: 5 Convection unit: 4 Electric heating: 4
Reset time (in min.)	Warm water heating: 150 Floor heating: 240 Convection unit: 90 Electric heating: 100

Now specify what should be sent when the control is blocked. Set a value greater 0 (=OFF) to receive a basic heating level, e.g. for floor heating.

On release, the control variable follows the rule again.

When blocked, the control variable shall	<ul><li>not be sent</li><li>send a specific value</li></ul>
Value (in %) ( <i>if a value is sent</i> )	<u>0</u> 100

In case of a common control variable for heating and cooling, 0 is always transmitted as a fixed value.

#### 2-point-control (only level 2):

2-point-control is used for systems which are only set to ON or OFF.

Control type	• 2-point-control
(is determined at a higher level for com-	
mon control variables)	

Enter the hysteresis that prevents frequent on/off switching of temperatures in the threshold range.

Hysteresis (in 0.1°C)	0100; 20
-----------------------	----------

If separate control variables are used, select whether the control variable of the 2nd level is a 1 bit object (on/off) or an 8 bit object (on with percentage/off).

Control variable is a	• 1 bit object • 8 bit object
Value (in %) (for 8 bit object)	0 <u>100</u>

Now specify what should be sent when the control is blocked. Set a value greater 0 (=OFF) to receive a basic heating level, e.g. for floor heating. On release, the control variable follows the rule again.

When blocked, the control variable shall	<ul><li>not be sent</li><li>send a specific value</li></ul>
Value (in %) only if a value is sent	<u>0</u> 100

# 8.3.2. Cooling control level 1/2

If a cooling control mode is configured, one or two setting sections for the cooling levels are displayed.

In the 1st level, cooling is controlled by a PI control in which either control parameters can be entered or predetermined applications can be selected.

In the 2nd level (therefore only for 2-level cooling), cooling is controlled via a PI or a 2-point-control.

In level 2, the setpoint deviation between the two levels must also be specified, i.e. above which setpoint value deviation the second level is added.

Setpoint difference between 1st and 2nd level (in 0.1°C) (for level 2)	0100; <u>40</u>
Control type (for level 2, no common control variables)	• 2-point-control • PI control
Control variable is a (for level 2 with 2-point controlling, no common control variables)	• <u>1 bit object</u> • 8 bit object

## PI control with control parameters:

This setting allows individual input of the parameters for PI control.

Control type	• PI control
Setting of the controller by	Controller parameter     specified applications

Specify the deviation from the setpoint value which reaches maximum variable value, i.e. the point at which maximum cooling power is activated.

The reset time shows how quickly the controller responds to deviations from the setpoint value. In case of a short reset time, the control responds with a fast increase of the control variable. In case of a long reset time, the control responds somewhat less urgently and needs longer until the necessary control variable for the setpoint value deviation is reached. You should set the time appropriate to the cooling system at this point (observe manufacturer's instructions).

Maximum control variable is reached at setpoint/actual difference of (in °C)	0 <u>5</u>
Reset time (in min.)	1255; <u>30</u>

Now specify what should be sent when the control is blocked. On release, the control variable follows the rule again.

When blocked, the control variable shall	<ul> <li>not be sent</li> <li>send a specific value</li> </ul>
Value (in %) ( <i>if a value is sent)</i>	<u>0</u> 100

In case of a common control variable for heating and cooling, 0 is always transmitted as a fixed value.

#### PI control with predetermined application:

This setting provides fixed parameters for a cooling ceiling

Control type	• PI control
Setting of the controller by	Controller parameter     specified applications
Application	Cooling ceiling
Maximum control variable is reached at setpoint/actual difference of (in °C)	Cooling ceiling: 5
Reset time (in min.)	Cooling ceiling: 30

Now specify what should be sent when the control is blocked. On release, the control variable follows the rule again.

When blocked, the control variable shall	<ul><li>not be sent</li><li>send a specific value</li></ul>
Value (in %) (if a value is sent)	<u>0</u> 100

#### 2-point-control (only level 2):

2-point-control is used for systems which are only set to ON or OFF.

Control type	• 2-point-control
is determined at a higher level for common	
variables	

Enter the hysteresis that prevents frequent on/off switching of temperatures in the threshold range.

If separate control variables are used, select whether the control variable of the 2nd level is a 1 bit object (on/off) or an 8 bit object (on with percentage/off).

Control variable is a	1 bit object     8 bit object
Value (in %) (for 8 bit object)	0 <u>100</u>

Now specify what should be sent when the control is blocked. On release, the control variable follows the rule again.

When blocked, the control variable shall	• <u>not be sent</u> • send a specific value
Value (in %) ( <i>if a value is sent)</i>	<u>0</u> 100

In case of a common control variable for heating and cooling, 0 is always transmitted as a fixed value.

# 8.3.3. Fan Coil Control

The fan coil control enables the regulation of the fan of convector heating/cooling systems.

Activate the fan coil control.

Use fan coil control	No • Yes
----------------------	----------

In fan coil control, the fan is automatically controlled by one or, in multi-level systems, several control variables for heating or cooling. Select which actuating variable(s) are to control the output. The selection depends on the type of heating/cooling control and the settings made for the actuating variables.

Output is controlled via actuating variable	Heating 1     Heating 2     Cooling 1     Cooling 2     Heating 1 and cooling 1     Heating 2 and cooling 1     Heating 1 and cooling 2     Heating 2 and cooling 2
---	---

Select whether the first fan level should also be on when the second and third level are running and whether the second fan level should also be on when the third level is running.

Switch Level 1 on also with Level 2 and 3	<u>No</u> • Yes
Switch Level 2 on also with Level 3	<u>No</u> • Yes

Set which mode is to be active after a reset.

Mode after reset	• Manual
	• Automatic (e.g. controller actuating varia-
	ble)

# 8.4. Temperature PI control – Controller extension unit

Activate the control

Use control

No • Yes

Determine if this device should take over the temperature control (stand-alone controller), or if the Cala display should act as an extension for operating another controller.

Intended as a	<ul> <li>Stand-alone controller</li> <li>Controller extension (for operating a</li> </ul>
	stand-alone controller only)

The settings for the 'controller extension' option are described below. For configuration as a stand-alone controller, please see Chapter *Temperature Pl control – Controller extension unit*, page 98.

The 'temperature controller' menu must be activated (see *Menus* > *Temperature control*, page 61) to enable the use of this controller type.

Set the type of mode switching and the controller. For more information about these functions, see setting the device as a stand-alone controller.

Switch mode via	• <u>two 8-bit objects (HVAC modes)</u> • three 1-bit objects
Type of control	<ul> <li><u>Single stage heating</u></li> <li>Dual-stage heating</li> <li>Single-stage cooling</li> <li>Dual-stage cooling</li> <li>Single-stage heating + single-stage cooling</li> <li>Dual-stage heating + single-stage cooling</li> <li>Dual-stage heating + dual-stage cooling</li> </ul>

You may enter separate set point values for each mode or use the comfort set point as a basic value. If you are using the basic value, only the deviation from the comfort set point value is listed for the other modes (e. g., 2 °C less for standby mode).

Setting the nominal values	<ul> <li>separately</li> <li>with comfort set point as a basis</li> </ul>
	•

If heating or cooling, specify how the status object should be analysed.

Analysis of the status object	• 0 = Heating 1 = Cooling
	• 1 = Heating   0 = Cooling

Activate fan coil control if a fan is used for heating/cooling.

Use fan coil control	No • Yes

Select whether the first fan stage should be switched on when the second and the third stages are on, and if the second fan stage should be switched on if the third stage is on.

Switch stage 1 on also if stages 2 and 3 are running	<u>No</u> •Yes
Switch stage 2 on if stage 3 is running	<u>No</u> • Yes

# 8.5. Summer Compensation

With the summer compensation the target value for the room temperature can automatically be adapted by cooling at higher outdoor temperatures. The objective is to prevent a too great a difference between indoor and outdoor temperature in order to keep the energy consumption low.

Activate the summer compensation.

Use summer compensation	No • Yes

Using the points 1 and 2, define the outdoor temperature range in which the target value for the indoor temperature is to be adapted linearly. Then, specify which indoor temperature target values are to be valid below point1 and above point 2.

#### Standard values according to DIN EN 60529

Point 1: External temperature = 20°, Target value = 20°C. Point 2: External temperature = 32°, Target value = 26°C.

Characteristic curve description:	
External temperature point 1 (in 0.1°C increments)	0 500 ; <u>200</u>
Outdoor temperature point 2 (in 0.1°C increments)	0 500 ; <u>320</u>
below point 1 the target value is (in 0.1°C)	0 500 ; <u>200</u>
above point 2 the target value is (in 0.1°C)	0 500 ; <u>260</u>

Set the send pattern for the summer compensation.

Send pattern	<ul> <li>periodically</li> <li><u>on change</u></li> <li>on change and periodically</li> </ul>
on change of (if sent on change)	0.1°C • <u>0.2°C</u> • 0.5°C • 1°C • 2°C • 5°C
Send cycle (if sent periodically)	5 s 2 h; <u>1 min</u>

If necessary, activate the block for the summer compensation and set what a 1 or 0 at the block input means and what happens in the event of a block.

Use block	<u>No</u> • Yes
Analysis of the blocking object	• At value 1: block   At value 0: release
	• At value 0: block   At value 1: release
Blocking object value before first call	<u>0</u> • 1
Action when locking	• do not send • Send value

Value (in increments of 0.1°C)	0 500; <u>200</u>
(if a value is sent during blocking)	

# 9. Humidity parameter settings

In the following all parameters are described that are found in devices with a humidity sensor, i.e. in

Cala KNX TH and Cala KNX AQS/TH.

# 9.1. Humidity Measurement

Select, whether a malfunction object is to be sent if the sensor is faulty.

Use malfunction object	<u>No</u> •Yes
------------------------	----------------

Use Offsets to adjust the readings to be sent.

Offset in 0.1% BH	-5050: 0

The unit can calculate a **mixed value** from its own reading and an external value. Set the mixed value calculation if desired. If an external portion is used, all of the following settings (threshold values, etc.) are related to the overall reading.

Use external measured value	<u>No</u> •Yes
Ext. Reading proportion of the total reading	5% • 10% • • <u>50%</u> • • 100%
Sending pattern for internal and total measured value	<ul> <li><u>never</u></li> <li>periodically</li> <li>on change</li> <li>on change and periodically</li> </ul>
At and above change of ( <i>if sent on change</i> )	0.1% RH ● 0.2% RH ● 0.5% RH ● <u>1.0% RH</u> ● ● 20.0% RH
Send cycle (if sent periodically)	5 s • <u>10 s</u> • • 2 h

The **minimum and maximum readings** can be saved and sent to the bus. Use the "Reset humidity min/max. value" objects to reset the values to the current readings. The values are not retained after a reset.

Use minimum and maximum value	No • Yes

# 9.2. Humidity threshold values

Activate the required air humidity threshold values. The menus for setting the threshold values are displayed.

Use threshold value 1/2/3/4 Yes • No

# 9.2.1. Threshold value 1, 2, 3, 4

# **Threshold value**

Set, in which cases **threshold values and delay times** received via objects are to be retained. The parameter is only taken into consideration if the setting via object is activated below. Please note that the setting "After power supply restoration and programming" should not be used for the initial start-up, as the factory settings are always used until the first communication (setting via objects is ignored).

Maintain the	
threshold values and delays received via communication objects	<ul> <li><u>never</u></li> <li>after power supply restoration</li> <li>after power supply restoration and programming</li> </ul>

Set the threshold value directly in the application program using parameters, or define them via the bus using a communication object.

#### Threshold value setting using parameter:

Set the threshold values and hysteresis directly.

Threshold value setting using	Parameter • Communication objects
Threshold value in 0.1% RH	1 1000; <u>650</u>

#### Threshold value setting using a communication object:

Define, how the threshold value is to be received from the bus. Basically, a new value can be received, or simply a command to increase or decrease.

During initial commissioning, a threshold value must be defined, which will be valid until the first communication with a new threshold value. For units which have already been taken into service, the last communicated threshold value can be used. Basically, a humidity range is specified in which the threshold value can be changed (object value limit).

A set threshold value will be retained until a new value or a change is transferred. The current value is saved, so that it is retained in the event of a power supply failure and will be available once the power supply is restored.

Threshold value setting using	Parameter • Communication objects
Starting threshold value in 0.1% RH valid until first communication	1 1000; <u>650</u>
Object value limit (min.) in 0.1%RH	<u>1</u> 1000
Object value limit (max.) in 0.1%RH	1 <u>1000</u>
Type of threshold value change	Absolute value
Increment (upon increase/decrease change)	0.1% RH • • <u>2.0% RH</u> • • 20.0% RH

Hysteresis settingin % • absoluteHysteresis in 0.1% RH0...1000; 100Hysteresis in %<br/>(relative to the threshold value)0 ... 50; 20

Set the **hysteresis** independent of the type of threshold value specification.

# **Switching output**

Set the behaviour of the switching output when a threshold value is exceeded/undercut. The output switching delay can be set using objects or directly as a parameter.

When the following conditions apply, the output is (TV = Threshold value)	<ul> <li><u>TV above = 1   TV - hyst. below = 0</u></li> <li><u>TV above = 0   TV - hyst. below = 1</u></li> <li><u>TV below = 1   TV + hyst. above = 0</u></li> <li><u>TV below = 0   TV + hyst. above = 1</u></li> </ul>
Delays can be set via objects (in seconds)	<u>No</u> • Yes
Switching delay from 0 to 1 (If delay can be set via objects: valid until 1st communication)	<u>None</u> • 1 s • 2 s • 5 s • 10 s • • 2 h
Switching delay from 1 to 0 (If delay can be set via objects: valid until 1st communication)	<u>None</u> • 1 s • 2 s • 5 s • 10 s • • 2 h
Switching output sends	<ul> <li>on change</li> <li>on change to 1</li> <li>on change to 0</li> <li>on change and periodically</li> <li>on change to 1 and periodically</li> <li>on change to 0 and periodically</li> </ul>
Cycle (is only sent if periodically is selected)	<u>5 s</u> • 10 s • 30 s • 2 h

# Block

The switching output can be blocked using an object.

Use switching output block	<u>No</u> • Yes
----------------------------	-----------------

If the block is activated, define specifications here for the behaviour of the output when blocked.

Analysis of the blocking object	At value 1: block   At value 0: release     At value 0: block   At value 1: release
Blocking object value before first communication	<u>0</u> •1
Behaviour of the switching output	
On block	• <u>Do not send message</u> • send 0 • send 1

On release	[Dependent on the "Switching output
(with 2 seconds release delay)	sends" setting]

The behaviour of the switching output on release is dependent on the value of the parameter "Switching output sends" (see "Switching output")

Switching output sends on change	<ul><li>Do not send message</li><li>Send switching output status</li></ul>
Switching output sends on change to 1	<ul> <li>Do not send message</li> <li>if switching output = 1 → send 1</li> </ul>
Switching output sends on change to 0	<ul> <li>Do not send message</li> <li>if switching output = 0 → send 0</li> </ul>
Switching output sends on change and periodically	Send switching output status
Switching output sends on change to 1 and periodically	if switching output = $1 \rightarrow$ send 1
Switching output sends on change to 0 and periodically	if switching output = $0 \rightarrow \text{send } 0$

# 9.3. Humidity PI control

If you activate humidity control, you can use the following settings to define control type, setpoint values, and humidification and dehumidification.

Use humidity control	No • Yes

# **General control**

**Room Controller Cala Touch KNX** can be used to control one- or two-level dehumidification or combined humidification/dehumidification.

Type of control	• One-level dehumidification
	<ul> <li>I wo-level dehumidification</li> </ul>
	<ul> <li>Humidification and dehumidification</li> </ul>

Configure a block for the humidity control using the blocking object.

Behaviour of the blocking object with value	• $\frac{1 = \text{Block} \mid 0 = \text{release}}{0 = \text{block} \mid 1 = \text{release}}$
Blocking object value before first communication	0 • <u>1</u>

Specify when the current control variables are to be sent to the bus. Periodic sending is safer, in case a message does not reach a recipient. You may also set up periodic monitoring using an actuator with this setting.

Send control variable	• on change
	<ul> <li>on change and periodically</li> </ul>

Send cycle	5 s • • <u>5 min</u> • • 2 h
(is only sent if "periodically" is selected)	

The status object shows the current status of the output variable (0 = OFF, >0 = ON) and can for example be used for visualisation.

Send status object(s)	<ul> <li><u>on change</u></li> <li>on change to 1</li> <li>on change to 0</li> <li>on change and periodically</li> <li>on change to 1 and periodically</li> <li>on change to 0 and periodically</li> </ul>
Send cycle (is only sent if "periodically" is selected)	5 s • • <u>5 min</u> • • 2 h

# **Controller setpoint**

Set, in which cases **setpoint values** received via object are to be retained. Please note that the setting "After power supply restoration and programming" should not be used for the initial start-up, as the factory settings are always used until the first communication (setting via objects is ignored).

Maintain the	
setpoint value received via communication object	<ul> <li><u>never</u></li> <li>after power supply restoration</li> <li>after power supply restoration and programming</li> </ul>

During initial commissioning, a **setpoint value** must be defined which is valid until the first communication of a new setpoint value. For units which have already been taken into service, the last communicated setpoint value can be used. Basically, an air humidity range is specified in which the setpoint value can be changed (**object value limit**).

Enter, how the setpoint value will be received from the bus. Basically, a new value can be received, or simply a command to increase or decrease.

A set setpoint value will be retained until a new value or a change is transferred. The current value is saved, so that it is retained in the event of a power supply failure and will be available once the power supply is restored.

Start setpoint in % valid until first communication (not upon saving the setpoint value after programming)	0 100; <u>50</u>
Object value limit (min.) in %	0100; <u>30</u>
Object value limit (max.) in %	0100; <u>70</u>
Type of setpoint value change	Absolute value • Increase/decrease
---------------------------------	------------------------------------
Increment	1% • <u>2%</u> • 3% • 5% • 10%
(upon increase/decrease change)	

In "Humidification and dehumidification" control mode, a dead zone is specified so that a direct changeover switching between humidification and dehumidification can be avoided.

Dead zone between humidification and	050; <u>10</u>
dehumidification in %	_
(only if both humidification and dehumidifi-	
cation are used)	

Humidification starts, when the relative air humidity is lower or equal to the setpoint value - dead zone value.

#### **Dehumidification and/or humidification**

Depending on the control mode, settings sections for humidification and dehumidification appear (level 1/2).

For dual-level dehumidification, the setpoint value difference between the two levels must be defined, i.e. the setpoint value which, when exceeded, triggers the switch to the 2nd level.

Target value difference between level 1	050; <u>10</u>
and 2 in %	
(for level 2 only)	

Determine the deviation from the setpoint value at which the maximum variable value is reached, i.e. the point at which maximum output is used.

The reset time shows how quickly the controller responds to deviations from the setpoint value. In case of a short reset time, the control responds with a fast increase of the control variable. In case of a long reset time, the control responds somewhat less urgently and needs longer until the necessary control variable for the setpoint value deviation is reached.

You should set the time appropriate for the humidification/dehumidification system at this point (note manufacturer instructions).

Maximum control variable is reached at target/actual difference of %	150; <u>5</u>
Reset time in minutes	1255; <u>3</u>

Now specify, what should be sent when the control is blocked. On release, the control variable follows the rule again.

When blocked, the control variable shall	<ul> <li>not be sent</li> <li>send a specific value</li> </ul>
Value in % ( <i>if a value is sent</i> )	<u>0</u> 100

### 9.4. Dewpoint measurement

The **Room Controller Cala Touch KNX** calculates the dewpoint temperature and can output the value to the bus.

Sending pattern	<ul> <li><u>never</u></li> <li>periodically</li> <li>on change</li> <li>on change and periodically</li> </ul>
At and above change of ( <i>if sent on change</i> )	0.1°C • 0.2°C • <u>0.5°C</u> • 1.0°C • 2.0°C • 5.0°C
Send cycle (if sent periodically)	5 s • <u>10 s</u> • 30 s • 1 min • • 2 h

Activate the monitoring of the coolant temperature if required. The menus for setting the monitoring are displayed.

Use monitoring of the coolant temperature No • Yes	3
--	---

### 9.4.1. Cooling medium temp. monitoring

A threshold value can be set for the temperature of the coolant, which is based on the current dewpoint temperature (offset/deviation). The switching output of the coolant temperature monitoring system can provide a warning prior to any build-up of condensation in the system, and/or activate appropriate countermeasures.

#### **Threshold value**

Threshold value = dewpoint temperature + offset

Set, in which cases **offset** received via object is to be retained. Please note that the setting "After power supply restoration and programming" should not be used for the initial start-up, as the factory settings are always used until the first communication (setting via objects is ignored).

Maintain the	
offset received via communication object	<ul> <li><u>never</u></li> <li>after power supply restoration</li> <li>after power supply restoration and programming</li> </ul>
•	

During initial commissioning, an **offset** must be defined which is valid until the first communication of a new offset. For units which have already been taken into service, the last communicated offset can be used.

A set offset will be retained until a new value or a change is transferred. The current value is saved, so that it is retained in the event of a power supply failure and will be available once the power supply is restored.

Start offset in °C valid until first communication	0200; <u>30</u>
Increment for offset change	$\frac{0.1^{\circ}\text{C}}{2^{\circ}\text{C}} \bullet 0.2^{\circ}\text{C} \bullet 0.3^{\circ}\text{C} \bullet 0.4^{\circ}\text{C} \bullet 0.5^{\circ}\text{C} \bullet 1^{\circ}\text{C} \bullet 2^{\circ}\text{C} \bullet 3^{\circ}\text{C} \bullet 4^{\circ}\text{C} \bullet 5^{\circ}\text{C}$
Hysteresis setting	in % • <u>absolute</u>
Hysteresis of the threshold value in % (for setting in %)	0 50; <u>20</u>
Threshold value hysteresis in 0.1°C increments (at absolute setting)	0 1000; <u>50</u>
Threshold value sends	<ul> <li><u>never</u></li> <li>periodically</li> <li>on change</li> <li>on change and periodically</li> </ul>
At and above change of ( <i>if sent on change</i> )	$\underline{0.1^{\circ}C} \bullet 0.2^{\circ}C \bullet 0.5^{\circ}C \bullet 1.0^{\circ}C \bullet 2.0^{\circ}C \bullet 5.0^{\circ}C$
Send cycle (if sent periodically)	5 s • <u>10 s</u> • 30 s • 1 min • • 2 h

#### **Switching output**

The output switching delay can be set using objects or directly as a parameter.

When the following conditions apply, the output is (TV = Threshold value)	<ul> <li>TV above = 1   TV - hyst. below = 0</li> <li>TV above = 0   TV - hyst. below = 1</li> <li><u>TV below = 1   TV + hyst. above = 0</u></li> <li>TV below = 0   TV + hyst. above = 1</li> </ul>
Delays can be set via objects (in seconds)	<u>No</u> • Yes
Switching delay from 0 to 1 for setting via objects: valid until 1st communication	<u>None</u> • 1 s • 2 s • 5 s • 10 s • • 2 h
Switching delay from 1 to 0 for setting via objects: valid until 1st communication	<u>None</u> • 1 s • 2 s • 5 s • 10 s • • 2 h
Switching output sends	<ul> <li><u>on change</u></li> <li>on change to 1</li> <li>on change to 0</li> <li>on change and periodically</li> <li>on change to 1 and periodically</li> <li>on change to 0 and periodically</li> </ul>
Send cycle (is only sent if periodically is selected)	<u>5 s</u> • 10 s • 30 s • 2 h

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### Blocking

The switching output can be blocked using an object. Define specifications here for the behaviour of the output when blocked.

Use switching output block	<u>No</u> •Yes	
Analysis of the blocking object	At value 1: block   At value 0: release	
	<ul> <li>At value 0: block   At value 1: release</li> </ul>	
Blocking object value before first communi- cation	<u>0</u> •1	
Behaviour of the switching output		
On block	• Do not send message	
	• send 0	
	• send 1	
On release (with 2 seconds release delay)	[Dependent on the "Switching output sends" setting]	

The behaviour of the switching output on release is dependent on the value of the parameter "Switching output sends" (see "Switching output")

Switching output sends on change	<ul><li>Do not send message</li><li>Send switching output status</li></ul>
Switching output sends on change to 1	<ul> <li>Do not send message</li> <li>if switching output = 1 → send 1</li> </ul>
Switching output sends on change to 0	<ul> <li>Do not send message</li> <li>if switching output = 0 → send 0</li> </ul>
Switching output sends on change and periodically	Send switching output status
Switching output sends on change to 1 and periodically	if switching output = $1 \rightarrow$ send 1
Switching output sends on change to 0 and periodically	if switching output = $0 \rightarrow \text{send } 0$

## 9.5. Absolute humidity

The absolute air humidity value is detected by the **Cala Touch KNX** and can be output to the bus.

Use absolute humidity	<u>No</u> • Yes
Sending pattern	<ul> <li><u>never</u></li> <li>periodically</li> <li>on change</li> <li>on change and periodically</li> </ul>
At and above change of ( <i>if sent on change</i> )	0.1 g • 0.2 g • <u>0.5 g</u> • 1.0 g • 2.0 g • 5.0 g
Send cycle (if sent periodically)	5 s • <u>10 s</u> • 30 s • 2 h

## 9.6. Comfort field

The **Room Controller Cala Touch KNX** can send a message to the bus if the limits of the comfort field are exceeded. In this way, it is for example possible to monitor compliance with DIN 1946 (standard values) or even to define your own comfort field.

Use comfort field	No • Yes

Specify the **sending pattern**, a **Text** for comfortable and uncomfortable and the **Object value**.

Sending pattern	<ul> <li><u>never</u></li> <li>periodically</li> <li>on change</li> <li>on change and periodically</li> </ul>
Text for comfortable	[Free text max. 14 chars.]
Text for uncomfortable	[Free text max. 14 chars.]
Object value is at	• comfortable = 1   uncomfortable = 0 • comfortable = 0   uncomfortable = 1
Send cycle (if sent periodically)	<u>5 s</u> • <u>10 s</u> • 30 s • 2 h

Define the comfort field by specifying the minimum and maximum values for temperature and humidity. The specified standard values comply with DIN 1946

Maximum temperature in °C (Standard 26°C)	25 40; <u>26</u>
Minimum temperature in °C (Standard 20°C)	10 21; <u>20</u>
Maximum relative humidity in % (Standard 65%)	52 90; <u>65</u>
Minimum relative humidity in % (Standard 30%)	10 43; <u>30</u>
Maximum absolute humidity in 0.1 g/kg (Standard 115 g/kg)	50 200; <u>115</u>

Temperature hysteresis: 1°C Relative humidity hysteresis: 2% RH Absolute humidity hysteresis: 2 g/kg

# 10. CO<sub>2</sub> parameter settings

In the following all parameters are described that are found in devices with a carbon dioxide sensor, i.e. in Cala KNX AQS/TH.

## 10.1. CO2 Measurement

Select, whether a **malfunction object** is to be sent if the sensor is faulty.

Use malfunction object	No • Yes
-	

Use Offsets to adjust the readings to be sent.

Offset in ppm	-100100; 0
	_

The unit can calculate a **mixed value** from its own reading and an external value. Set the mixed value calculation if desired. If an external portion is used, all of the following settings (threshold values, etc.) are related to the overall reading.

Use external measured value	<u>No</u> •Yes
Ext. Reading proportion of the total reading	5% • 10% • • <u>50%</u> • • 100%
Sending pattern for internal and total measured value	<ul> <li><u>never</u></li> <li>periodically</li> <li>on change</li> <li>on change and periodically</li> </ul>
At and above change of (relative to the last measured value) ( <i>if sent on change</i> )	2% • <u>5%</u> • • 50%
Send cycle (if sent periodically)	5 s • <u>10 s</u> • • 2 h

The **maximum reading** can be saved and sent to the bus. Using the "Reset CO2 maximum value" objects, the value can be reset to the current reading. The value is not retained after a reset.

## 10.2. CO2 threshold values

Activate the required CO2 threshold value. The menus for setting the threshold values are displayed.

Use threshold value 1/2/3/4	Yes • No

300 ppm ... 1000 ppm: fresh air 1000 ppm ... 2000 ppm: used air

1000 ppm = 0.1 %

### 10.2.1. Threshold value 1, 2, 3, 4

#### Threshold value

Set, in which cases **threshold values and delay times** received via object are to be retained. The parameter is only taken into consideration if the setting via object is activated below. Please note that the setting "After power supply restoration and programming" should not be used for the initial start-up, as the factory settings are always used until the first communication (setting via objects is ignored).

Maintain the	
threshold values and delays received via communication objects	<ul> <li><u>never</u></li> <li>after power supply restoration</li> <li>after power supply restoration and programming</li> </ul>

Set the threshold value directly in the application program using parameters, or define them via the bus using a communication object.

#### Threshold value setting using parameters:

Set the threshold values and hysteresis directly.

Threshold value setting using	Parameter • Communication objects
Threshold value in ppm	0 2000; <u>1200</u>

#### Threshold value setting using a communication object:

Define, how the threshold value will be received from the bus. Basically, a new value can be received, or simply a command to increase or decrease.

During initial commissioning, a threshold value must be defined, which will be valid until the first communication of a new threshold value. For units which have already been taken into service, the last communicated threshold value can be used. Basically, a range is specified in which the threshold value can be changed (object value limit).

A set threshold value will be retained until a new value or a change is transferred. The current value is saved, so that it is retained in the event of a power supply failure and will be available once the power supply is restored.

Threshold value setting using	Parameter • Communication objects
Start threshold value in 0.1°C valid until first communication	-300 800; <u>200</u>
Limitation of object value (min) in ppm	<u>10</u> 2000
Limitation of object value (max) in ppm	12000; <u>1000</u>
Type of threshold value change	Absolute value
Increment in ppm (upon increase/decrease change)	1 • 2 • 5 • 10 • <u>20</u> • • 200

Hysteresis settingin % • absoluteHysteresis in ppm0...2000; 500Hysteresis in % of the threshold value0 ... 50; 20

Set the **hysteresis** independent of the type of threshold value specification.

#### **Switching output**

Set the behaviour of the switching output when a threshold value is exceeded/undercut. The output switching delay can be set using objects or directly as a parameter.

When the following conditions apply, the output is (TV = Threshold value)	<ul> <li>TV above = 1   TV - hyst. below = 0</li> <li>TV above = 0   TV - hyst. below = 1</li> <li>TV below = 1  TV + hyst. above = 0</li> <li>TV below = 0  TV + hyst. above = 1</li> </ul>
Delays can be set via objects (in seconds)	<u>No</u> • Yes
Switching delay from 0 to 1 (If delay can be set via objects: valid until first communication)	<u>None</u> • 1 s • 2 s • 5 s • 10 s • • 2 h
Switching delay from 1 to 0 (If delay can be set via objects: valid until first communication)	<u>None</u> • 1 s • 2 s • 5 s • 10 s • • 2 h
Switching output sends	<ul> <li>on change</li> <li>on change to 1</li> <li>on change to 0</li> <li>on change and periodically</li> <li>on change to 1 and periodically</li> <li>on change to 0 and periodically</li> </ul>
Cycle (is only sent if periodically is selected)	<u>5 s</u> • 10 s • 30 s • 2 h

### Block

The switching output can be blocked using an object.

Use switching output block	No • Yes
0 1	

If the block is activated, define specifications here for the behaviour of the output when blocked.

Analysis of the blocking object	At value 1: block   At value 0: release     At value 0: block   At value 1: release
Blocking object value before first communication	<u>0</u> • 1
Behaviour of the switching output	
On block	• <u>Do not send message</u> • send 0 • send 1

On release	[Dependent on the "Switching output
(with 2 seconds release delay)	sends" setting]

The behaviour of the switching output on release is dependent on the value of the parameter "Switching output sends" (see "Switching output")

Switching output sends on change	<ul><li>Do not send message</li><li>Send switching output status</li></ul>
Switching output sends on change to 1	<ul> <li>Do not send message</li> <li>if switching output = 1 → send 1</li> </ul>
Switching output sends on change to 0	<ul> <li>Do not send message</li> <li>if switching output = 0 → send 0</li> </ul>
Switching output sends on change and periodically	Send switching output status
Switching output sends on change to 1 and periodically	if switching output = $1 \rightarrow$ send 1
Switching output sends on change to 0 and periodically	if switching output = $0 \rightarrow \text{send } 0$

## 10.3. CO2 PI-control

If you activate air quality control, you can use the following settings to define control type, setpoint values, and ventilation.

Use control	Yes • No

### **General control**

The **Room Controller Cala Touch KNX** can be used to control one or two-stage ventilation.

Type of control	One-stage ventilation
	<ul> <li>Two-stage ventilation</li> </ul>

Configure a block for the ventilation control using the blocking object.

Behaviour of the blocking object with value	• $\frac{1 = \text{Block} \mid 0 = \text{release}}{0 = \text{block} \mid 1 = \text{release}}$
Blocking object value before first communication	0 • <u>1</u>

Specify when the current control variables are to be sent to the bus. Periodic sending is safer, in case a message does not reach a recipient. You may also set up periodic monitoring using an actuator with this setting.

Send control variable	<ul> <li><u>on change</u></li> <li>on change and periodically</li> </ul>
at and above change of (in ppm)	120; <u>2</u>
Cycle ( <i>if sent periodically</i> )	5 s • • <u>5 min</u> • • 2 h

 

 Send status object(s)
 • on change • on change to 1 • on change to 0 • on change and periodically • on change to 1 and periodically • on change to 0 and periodically

 Cycle (if sent periodically)
 5 s • 10 s • ... • 2 h

The status object shows the current status of the output variable (0 = OFF, >0 = ON) and can for example be used for visualisation.

#### **Controller setpoint**

The setpoint values can be set directly in the application program using parameters, or be defined via the bus using a communication object.

#### Setpoint value setting using parameters:

Set the setpoint value directly.

Specified setpoint using	Parameter • Communication objects
Target value in ppm	4005000; <u>800</u>

#### Setpoint value setting via communication object:

Enter, how the setpoint value will be received from the bus. Basically, a new value can be received, or simply a command to increase or decrease.

During initial commissioning, a setpoint value must be defined which is valid until the first communication of a new setpoint value. For units which have already been taken into service, the last communicated setpoint value can be used. Basically, an air humidity range is given in which the setpoint value can be changed (object value limit).

A set setpoint value will be retained until a new value or a change is transferred. The current value is saved, so that it is retained in the event of a power supply failure and will be available once the power supply is restored.

Threshold value setting using	Parameter • Communication objects
The last communicated value should be retained	<u>never</u> after power supply restoration     after power supply restoration and     programming
Start setpoint value in ppm valid until first communication (not upon saving the setpoint value after programming)	400 2000; <u>800</u>
Object value limit (min) in 0.1°C	4002000; <u>400</u>
Object value limit (max) in 0.1°C	4002000; <u>1500</u>

Type of threshold value change	Absolute value
Increment in ppm	1 • 2 • 5 • • <u>20</u> • • 100 • 200
(upon increase/decrease change)	

#### Ventilation control

Depending on the control mode, one and/or two setting sections for the ventilation stages are displayed.

For two-stage ventilation, the setpoint value difference between the two stages must be defined, i.e. the setpoint value which, when exceeded, triggers the switch to the 2nd level.

2nd level in ppm (for level 2 only)	Target value difference between 1st and	1002000; 400
(for level 2 only)	2nd level in ppm	
	(for level 2 only)	

Determine the deviation from the setpoint value at which the maximum variable value is reached, i.e. the point at which maximum output is used.

The reset time shows how quickly the controller responds to deviations from the setpoint value. In case of a short reset time, the control responds with a fast increase of the control variable. In case of a long reset time, the control responds somewhat less urgently and needs longer until the necessary control variable for the setpoint value deviation is reached.

You should set the time appropriate to the ventilation system at this point (follow the manufacturer's instructions).

Maximum control variable is reached at setpoint value/actual difference of (in ppm)	<u>100</u> 2000
Reset time in minutes	1255; <u>30</u>

Now specify what should be sent when the control is blocked. On release, the control variable follows the rule again.

When blocked, the control variable shall	<ul> <li>not send anything</li> <li>send a value</li> </ul>
Value in % ( <i>if a value is sent</i> )	<u>0</u> 100



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